

SOME SOLUTIONS FOR AN EQUATION OF ORDER OF 4p

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Abstract- We obtain all solutions which depend only on r for a singular partial differential equation of order $4p$. Here, the operator includes Laplacian and GASPT (Generalized Axially Symmetric Potential Theory) operator.

Keywords- Singular equation, Solution of type r^m , Laplacian, GASPT operator.

1. INTRODUCTION

This paper consists of solutions of type r^m for the linear partial differential equation of order of $4p$

$$L^p(u) = 0 \tag{1.1}$$

where p is a positive integer and the singular operator L is defined by

$$L = r^2 \sum_{i=1}^n \left\{ \frac{\lambda a_i^6 r^2}{(x_i - x_i^0)^2} \frac{\partial^4}{\partial x_i^4} + \left[\frac{\mu a_i^4}{x_i - x_i^0} - \frac{\lambda a_i^6 r^2}{(x_i - x_i^0)^3} \right] \frac{\partial^3}{\partial x_i^3} \right\} + \sum_{i=1}^n \left(a_i^2 \frac{\partial^2}{\partial x_i^2} + \frac{\alpha_i}{x_i - x_i^0} \frac{\partial}{\partial x_i} \right) + \frac{\gamma}{r^2} \tag{1.2}$$

The iterated operators L^p are defined by the relations

$$L^{k+1}(u) = L[L^k(u)]; \quad k = 1, \dots, p-1$$

In (1.2) x_i^0 , $a_i \neq 0$ ($i=1, \dots, n$) are real constants and $\lambda, \mu, \gamma, \alpha_i$ ($i=1, \dots, n$) are any real parameters and r is given by

$$r = \left[\sum_{i=1}^n \left(\frac{x_i - x_i^0}{a_i} \right)^2 \right]^{1/2}, \quad r > 0 \quad (1.3)$$

Equation (1.1) includes some well-known classical equations such as the Laplace equation, GASPT equation and their iterated forms. Many authors studied these equations in solving some physical problems [1-5].

2. SOLUTIONS OF TYPE r^m

Firstly, we will give the following lemma.

Lemma 2.1 Let p be a positive integer and m be a real or complex parameter. Then

$$L^p(r^m) = \prod_{k=0}^{p-1} \Phi(m-2k)r^{m-2p} \quad (2.1)$$

where $\Phi(m)$ is a fourth degree polynomial given by

$$\begin{aligned} \Phi(m) = & \lambda m^4 + (5\lambda n - 12\lambda + \mu)m^3 + (44\lambda - 30\lambda n + 3n\mu - 6\mu + 1)m^2 \\ & + (40\lambda n - 48\lambda - 6n\mu + 8\mu + n - 2 + \rho)m + \gamma \end{aligned} \quad (2.2)$$

$$\text{with } \rho = \sum_{i=1}^n \frac{\alpha_i}{a_i}.$$

Proof. From the definitions of L and r for any real or complex parameter m , we have

$$\begin{aligned} L(r^m) &= \left[\lambda m^4 + (5\lambda n - 12\lambda + \mu)m^3 + (44\lambda - 30\lambda n + 3n\mu - 6\mu + 1)m^2 \right. \\ &\quad \left. + (40\lambda n - 48\lambda - 6n\mu + 8\mu + n - 2 + \rho)m + \gamma \right] r^{m-2} \\ &= \Phi(m)r^{m-2} \end{aligned} \quad (2.3)$$

Applying the operator L consecutively $p-1$ times on both sides of (2.3), we obtain the formula (2.1).

Now consider the formula (2.1) and write the algebraic polynomial equation

$$\prod_{k=0}^{p-1} \Phi(m-2k) = 0 \quad (2.4)$$

which is degree of $4p$. The number of real or complex roots of the equation (2.4) is $4p$ for $\lambda \neq 0$.

Now using Lemma 2.1, we can prove the following theorem.

Theorem 2.1 Let the algebraic polynomial equation (2.4) have distinct roots c_1, c_2, \dots, c_M each having multiplicity $\xi_1, \xi_2, \dots, \xi_M$, respectively, and all of the roots be real. Then the solution of type r^m for the equation (1.1) is given by the formula

$$u(r) = \sum_{j=1}^M \sum_{v=0}^{\xi_j-1} A_{jv} r^{c_j} (\ln r)^v \quad (2.5)$$

where A_{jv} are arbitrary constants.

Proof. According to the hypothesis we can write the algebraic equation (2.4) as

$$\lambda^p \prod_{j=1}^M (m - c_j)^{\xi_j} = 0$$

where $\sum_{j=1}^M \xi_j = 4p$ is degree of (2.4). Therefore, the formula (2.1) can be written as

$$L^p(r^m) = \lambda^p \prod_{j=1}^M (m - c_j)^{\xi_j} r^{m-2p} \quad (2.6)$$

On the other hand, truth of the following equalities can be showed easily by induction.

$$\frac{\partial^k}{\partial m^k} [L^p(r^m)] = L^p \left(\frac{\partial^k r^m}{\partial m^k} \right) = L^p [r^m (\ln r)^k], \quad k \in \mathbb{N} \quad (2.7)$$

Now again consider (2.6). It is obvious that the right-hand side of (2.6) has the factors $(m - c_j)^{\xi_j}$; $j=1, \dots, M$ which vanish for $m = c_j$; $j=1, \dots, M$ together with its derivatives with respect to m

$$\frac{d^v}{dm^v} (m - c_j)^{\xi_j}; \quad v = 1, \dots, \xi_j - 1, \quad j = 1, \dots, M.$$

Thus, the functions r^{c_j} for $j=1, \dots, M$ and from (2.7) each of the functions

$$\left. \frac{\partial^v r^m}{\partial m^v} \right|_{m=c_j} = r^{c_j} (\ln r)^v; \quad v = 1, \dots, \xi_j - 1, \quad j = 1, \dots, M$$

satisfy the equation (1.1). Since the given equation is linear, by the superposition principle the sum

$$u(r) = \sum_{j=1}^M \sum_{v=0}^{\xi_j-1} A_{jv} r^{c_j} (\ln r)^v$$

also satisfies (1.1). Thus, the theorem is proved.

Theorem 2.2 Let the algebraic polynomial equation (2.4) have distinct roots $\alpha_1 \pm i\beta_1, \alpha_2 \pm i\beta_2, \dots, \alpha_N \pm i\beta_N$ each having multiplicity $\tau_1, \tau_2, \dots, \tau_N$, respectively, and all of the roots be complex. Then the solution of type r^m for equation (1.1) is given by the formula

$$u(r) = \sum_{s=1}^N \sum_{q=0}^{\tau_s-1} r^{\alpha_s} (\ln r)^q \left[B_{sq} \cos(\beta_s \ln r) + C_{sq} \sin(\beta_s \ln r) \right] \quad (2.8)$$

where B_{sq} ve C_{sq} are arbitrary constants.

Proof. Similar to Theorem 2.1, we can write (2.1) as

$$L^p(r^m) = \lambda^p \prod_{s=1}^N (m^2 - 2\alpha_s m + \alpha_s^2 + \beta_s^2)^{\tau_s} r^{m-2p} \quad (2.9)$$

where $2 \sum_{s=1}^N \tau_s = 4p$. The factors

$$(m^2 - 2\alpha_s m + \alpha_s^2 + \beta_s^2)^{\tau_s} = [m - (\alpha_s + i\beta_s)]^{\tau_s} [m - (\alpha_s - i\beta_s)]^{\tau_s}; s=1, \dots, N$$

which are on the right-hand side of (2.9) and the following derivatives of these factors

$$\frac{d^q}{dm^q} [m - (\alpha_s \pm i\beta_s)]^{\tau_s}; q=1, \dots, \tau_s - 1, s=1, \dots, N$$

are zero for $m = \alpha_s \pm i\beta_s$. Therefore, for $s=1, \dots, N$ each of the functions $r^{\alpha_s \pm i\beta_s}$ and, from (2.7) and the following expression

$$r^{\alpha_s \pm i\beta_s} = r^{\alpha_s} r^{\pm i\beta_s} = r^{\alpha_s} e^{\pm i\beta_s \ln r} = r^{\alpha_s} [\cos(\beta_s \ln r) \pm i \sin(\beta_s \ln r)]$$

for $q=1, \dots, \tau_s - 1, s=1, \dots, N$ each of the functions

$$\left. \frac{\partial^q r^m}{\partial m^q} \right|_{m=\alpha_s \pm i\beta_s} = r^{\alpha_s \pm i\beta_s} (\ln r)^q = r^{\alpha_s} (\ln r)^q [\cos \beta_s (\ln r) \pm i \sin \beta_s (\ln r)]$$

satisfy the equation (1.1). Since the given equation is linear, by the superposition principle the sum (2.8) also satisfies (1.1).

Now, we can give the following theorem which is a result of the Theorem 2.1 and Theorem 2.2. Proof of the theorem is similar to the previous theorems.

Theorem 2.3 Let the algebraic polynomial equation (2.4) have distinct real roots c_1, c_2, \dots, c_M , each having multiplicity $\xi_1, \xi_2, \dots, \xi_M$, respectively, and distinct complex roots $\alpha_1 \pm i\beta_1, \alpha_2 \pm i\beta_2, \dots, \alpha_N \pm i\beta_N$, each having multiplicity $\tau_1, \tau_2, \dots, \tau_N$, respectively. Then the solutions of type r^m for equation (1.1) is given by the formula

$$u(r) = \sum_{j=1}^M \sum_{v=0}^{\xi_j-1} A_{jv} r^{c_j} (\ln r)^v + \sum_{s=1}^N \sum_{q=0}^{\tau_s-1} r^{\alpha_s} (\ln r)^q [B_{sq} \cos(\beta_s \ln r) + C_{sq} \sin(\beta_s \ln r)] \quad (2.10)$$

where A_{jv}, B_{sq} ve C_{sq} are arbitrary constants.

Example 2.1 Consider the following operator L

$$L = r^4 \left[\frac{1}{(x+1)^2} \frac{\partial^4}{\partial x^4} + \frac{64}{(y-3)^2} \frac{\partial^4}{\partial y^4} - \frac{1}{(x+1)^3} \frac{\partial^3}{\partial x^3} - \frac{64}{(y-3)^3} \frac{\partial^3}{\partial y^3} \right. \\ \left. + \frac{\partial^2}{\partial x^2} + 4 \frac{\partial^2}{\partial y^2} + \frac{2}{x+1} \frac{\partial}{\partial x} - \frac{8}{y-3} \frac{\partial}{\partial y} - \frac{16}{r^2} \right] \quad (2.11)$$

where $r^2 = (x+1)^2 + \frac{(y-3)^2}{4}$.

Now, we obtain solution of type r^m for equation $L^2(u) = 0$. If we substitute $\lambda = 1, \mu = 0, a_1 = 1, a_2 = -2, \alpha_1 = 2, \alpha_2 = -8, \gamma = -16, x_1^0 = -1, x_2^0 = 3$ which are the parameter values in the operator (2.11) in (2.2), we then find

$$\begin{aligned} \phi(m) &= m^4 - 2m^3 - 15m^2 + 32m - 16 \\ &= (m+4)(m-1)^2(m-4) \end{aligned}$$

and we can write from (2.1)

$$\begin{aligned} L^2(r^m) &= \phi(m)\phi(m-2)r^{m-4} \\ &= \{(m+4)(m+2)(m-1)^2(m-3)^2(m-4)(m-6)\}r^{m-4} \end{aligned}$$

Therefore, algebraic polynomial equation is

$$(m+4)(m+2)(m-1)^2(m-3)^2(m-4)(m-6) = 0$$

From this equation we obtain $c_1 = 6$, $c_2 = 4$, $c_3 = 3$, $c_4 = 1$, $c_5 = -2$, $c_6 = -4$, $\xi_1 = 1$, $\xi_2 = 1$, $\xi_3 = 2$, $\xi_4 = 2$, $\xi_5 = 1$, $\xi_6 = 1$. If these values are substituted in (2.5) we then have

$$\begin{aligned} u(r) &= \sum_{j=1}^6 \sum_{v=0}^{\xi_j-1} A_{jv} r^{c_j} (\ln r)^v = A_{10} r^6 + A_{20} r^4 + A_{30} r^3 + A_{31} r^3 (\ln r) \\ &\quad + A_{40} r + A_{41} r (\ln r) + A_{50} r^{-2} + A_{60} r^{-4} \end{aligned}$$

solution of type r^m for $L^2(u) = 0$.

3. SOLUTIONS OF TYPE $u = u(r)$

In this section, we will show that all solutions which depend only on r for the equation (1.1) can be expressed by formula (2.10).

Theorem 3.1 All solutions of type $u = u(r)$ for equation (1.1) can be expressed by the formula (2.10).

Proof. Consider the operator (1.2). Applying the operator L to the function $u = u(r)$, we obtain

$$\begin{aligned} L(u) &= \lambda r^2 \frac{d^4 u}{dr^4} + (5\lambda n - 6\lambda + \mu) r \frac{d^3 u}{dr^3} + (15\lambda - 15\lambda n + 3\mu n - 3\mu + 1) \frac{d^2 u}{dr^2} \\ &\quad + (15\lambda n - 15\lambda + 3\mu - 3\mu n + n - 1 + \rho) r^{-1} \frac{du}{dr} + \frac{\gamma u}{r^2} \end{aligned} \quad (3.1)$$

Since the above operator is an Euler type operator, if we set $r = e^t$ and $D = \frac{d}{dt}$, then we have

$$\begin{aligned} L(u) &= L(D)u = e^{-2t} [\lambda D^4 + (5\lambda n - 12\lambda + \mu) D^3 + (44\lambda - 30\lambda n + 3\mu n - 6\mu + 1) D^2 \\ &\quad + (40\lambda n - 48\lambda + 8\mu - 6\mu n + n - 2 + \rho) D + \gamma] u \\ &= e^{-2t} \Phi(D)u \end{aligned} \quad (3.2)$$

Applying the operator L on both sides of (3.2), we find

$$L^2(u) = L^2(D)u = L(D)\{e^{-2t}\Phi(D)u\} = e^{-2t}\Phi(D)\{e^{-2t}\Phi(D)u\} \quad (3.3)$$

From ordinary differential equations, we know that, for any polynomials of the operator D with constant coefficients G and H and for a constant α , the following relation is valid [1].

$$G(D)\{e^{-\alpha t}H(D)u\} = e^{-\alpha t}G(D - \alpha)H(D)u$$

Considering this property, (3.3) can be written as

$$\begin{aligned} L^2(u) &= L^2(D)u = e^{-2t}\Phi(D)\{e^{-2t}\Phi(D)u\} \\ &= e^{-4t}\Phi(D-2)\Phi(D)u \end{aligned} \quad (3.4)$$

We remark that the product of $\Phi(D-2)$ and $\Phi(D)$ is commutative. Applying the operator L repeatedly $p-2$ times on both sides of (3.4), then we obtain

$$L^p(u) = e^{-2pt} \prod_{k=0}^{p-1} \Phi(D-2k)u \quad (3.5)$$

Equating the expression (3.5) to zero, we obtain an ordinary differential equation with constant coefficients and of order $4p$. The indicial equation for this equation is

$$\prod_{k=0}^{p-1} \Phi(m-2k) = 0$$

This was obtained previously on the right-hand side of (2.1). It is obvious that the corresponding solution for this equation is given by (2.10).

We note that, if we substitute $u = r^m$ in (3.5) then, by considering $r^m = e^{mt}$ and $e^{-2pt} = r^{-2p}$ and $\prod_{k=0}^{p-1} \Phi(D-2k)e^{mt} = e^{mt} \prod_{k=0}^{p-1} \Phi(m-2k)$, we see that (3.5) reduces to (2.1).

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