



Understanding OpenRelief



Planning disaster relief efforts is like trying to see through fog.





OpenRelief is a project to develop better communications tools for disaster relief efforts: the tools to clear the fog.





OpenRelief solutions will gather critical information for relief workers on the ground





This information will help the right aid to get to the right places at the right time.





Our first step is to create a robot plane to investigate and map disaster zones.

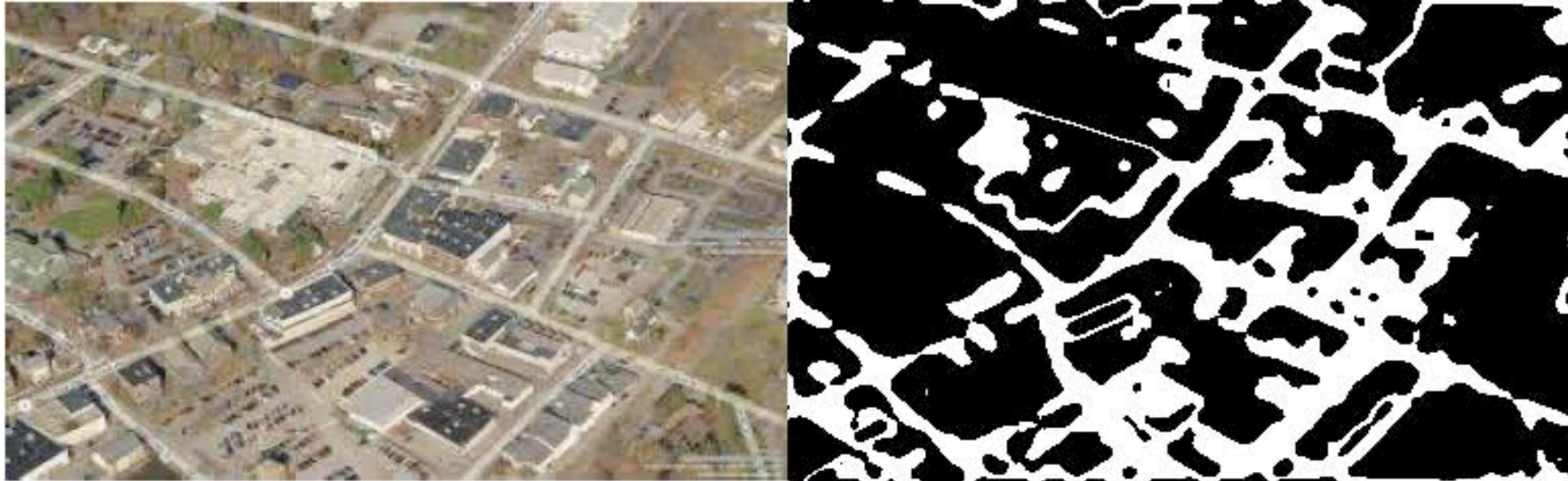


What The Plane Does

- It can take off from footpaths.
- It can recognize roads, people and smoke.
- It can photograph, film and map the landscape.
- It can measure weather, radiation and other conditions via modular sensors.



Seeing Stuff



How The Plane Is Made



- Many off-the-shelf components.
- Open Hardware computer, autopilot and sensors.
- Free and Open Source Software throughout.



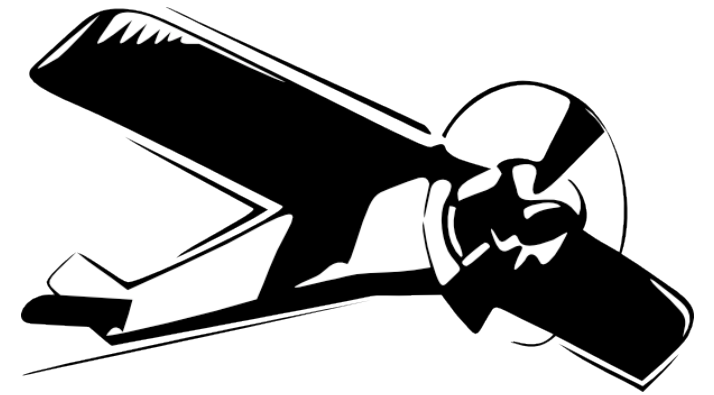






The Airframe

- Body: Fiberglass and balsa wood.
- Wing Span: 1660mm.
- Fuselage: 1190mm.
- Weight: 2 - 3kg.
- 20 - 30 minutes endurance.



The System

- Ardupilot Mega to fly the plane.
- Super HAD CDD fisheye camera to see.
- Arduino-based sensors to gather information.
- Raspberry Pi to process data.
- Debian OS to analyze the results.



Autopilot Specs

- 16MHz Atmega2560 processor.
- 256k Flash Program Memory, 8K SRAM, 4K EEPROM.
- 600 3D waypoints and mission commands.
- 16MB Data Logger (Black Box).
- Can reboot the processor in mid-flight.



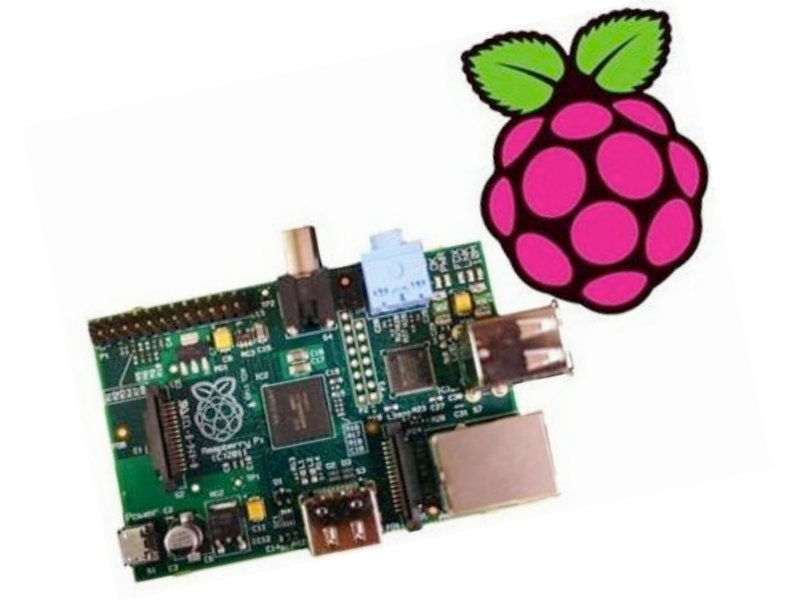
Camera Module Specs

- Sensor: 1/3" Sony Super HAD ii CCD
- Lens: 1.78mm | 70 degree view angle.
- Minimum Light: 0.1 Lux at F1.2.
- Auto Tracking White Balance.
- Operating Temp.: -10°C ~ +50°C



Computer Specs

- BCM2835 700 MHz ARM11
- 256-MB LPDDR RAM.
- 1080p30 H.264 encode/decode, HDMI.
- GPIO pins, Serial Bus (SPI), UART and 10/100 wired Ethernet RJ45.
- SD / MMC / SDIO card support.

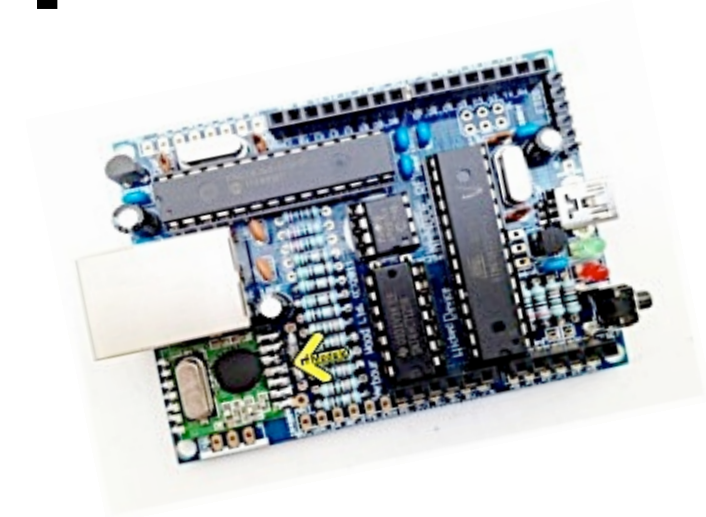


Software Specs

- ArduPlane 2.32 (autopilot).
- Debian 6 (OS).
- OpenCV 2.3.1 (visual recognition).
- Custom code for smoke, people, roads and SfM (structure from motion).



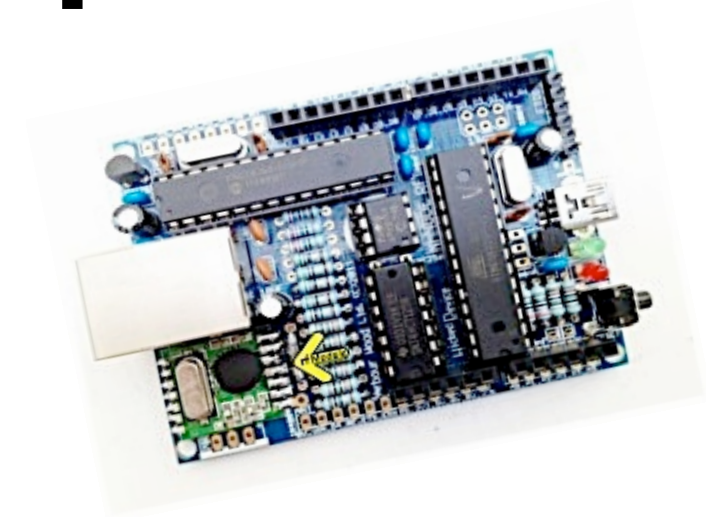
Weather Module Specs



- Nanode RF:
 - ATmega328p 8-bit RISC microprocessor.
 - RFM12B radio module (100 meter range).
- Off-the-shelf sensors with RJ11 terminated cables.

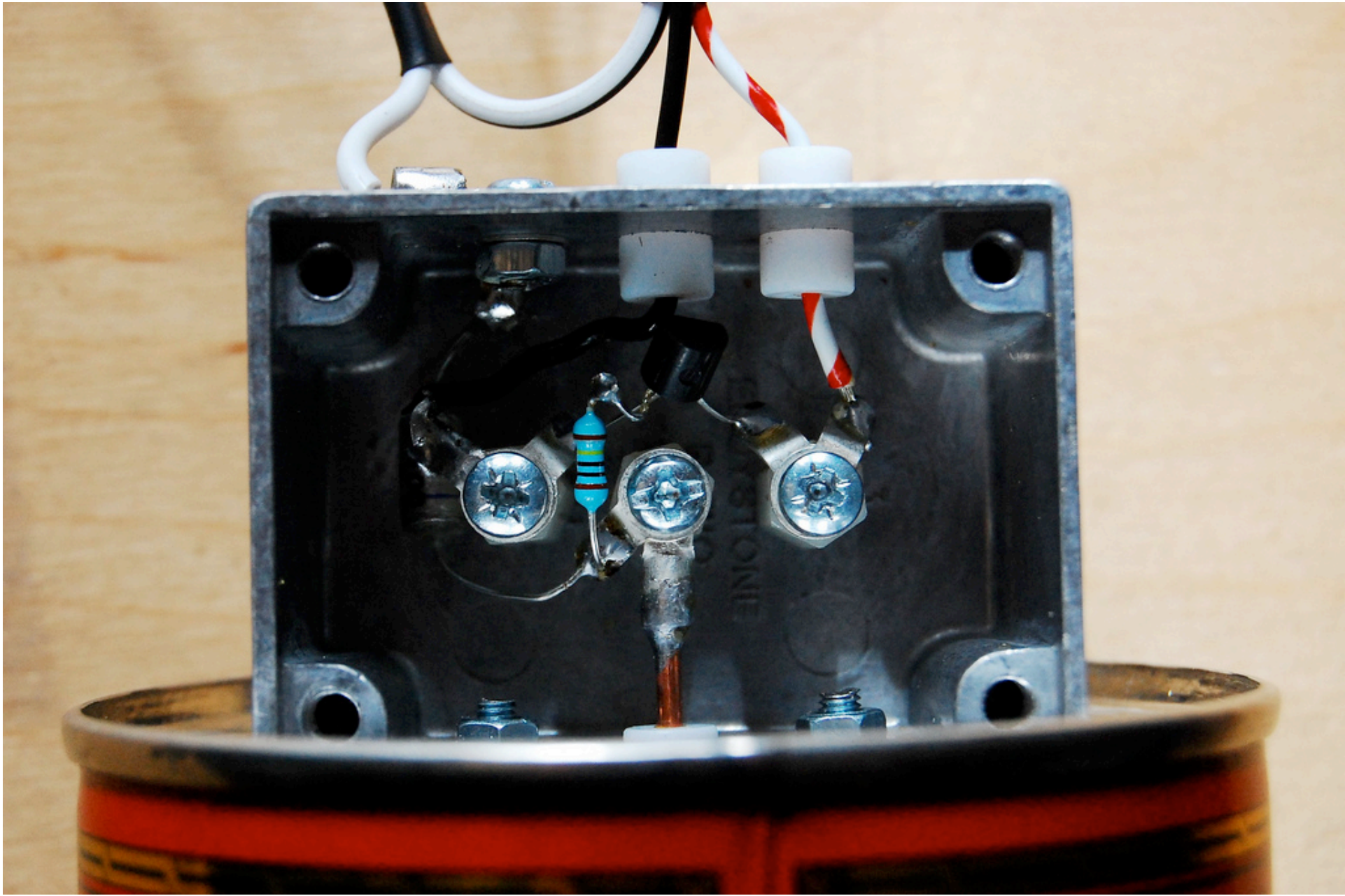


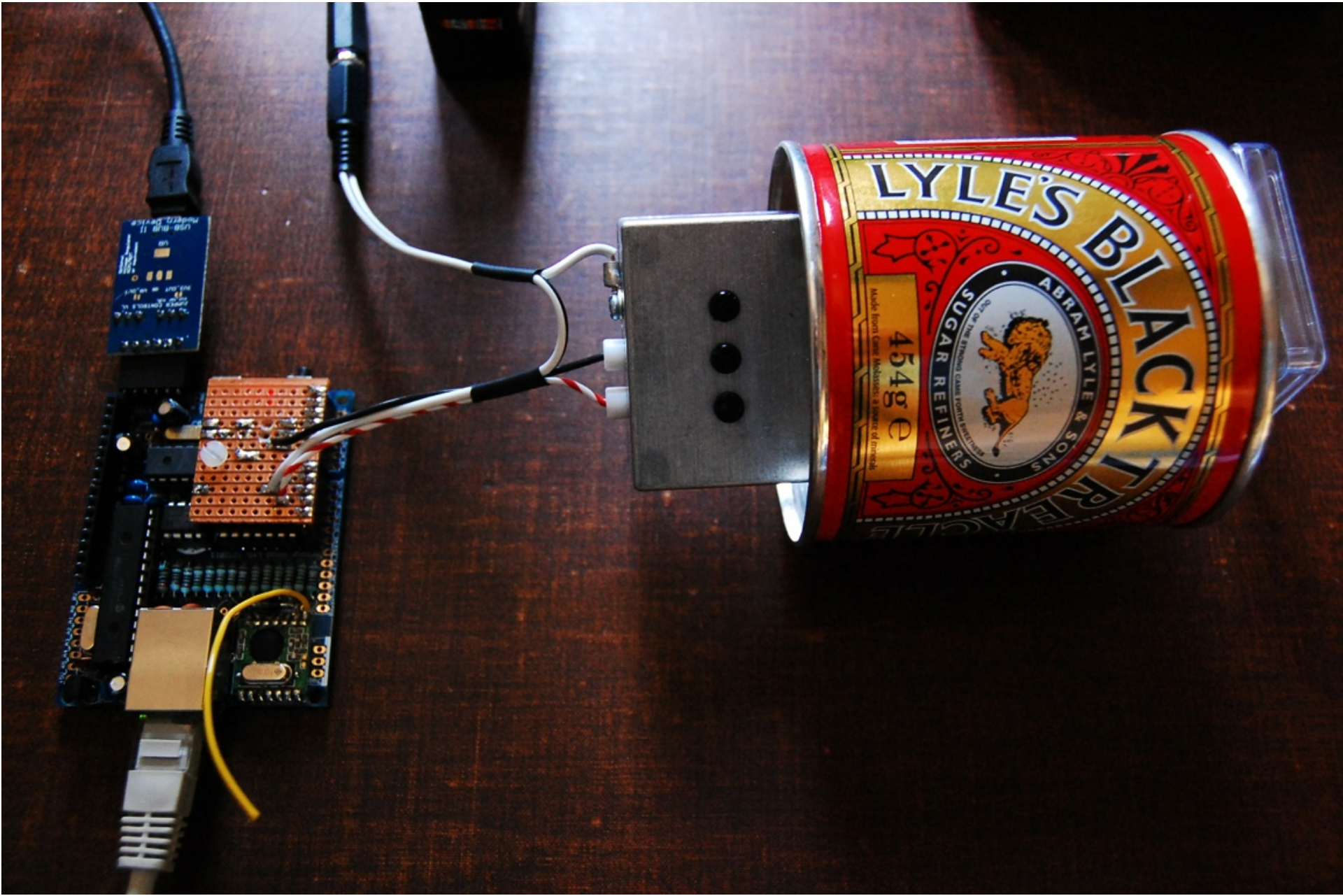
Radiation Module Specs



- Nanode RF:
 - ATmega328p 8-bit RISC microprocessor.
 - RFM12B radio module (100 meter range).
- Custom Ionization chamber or J305 β Geiger Tube.





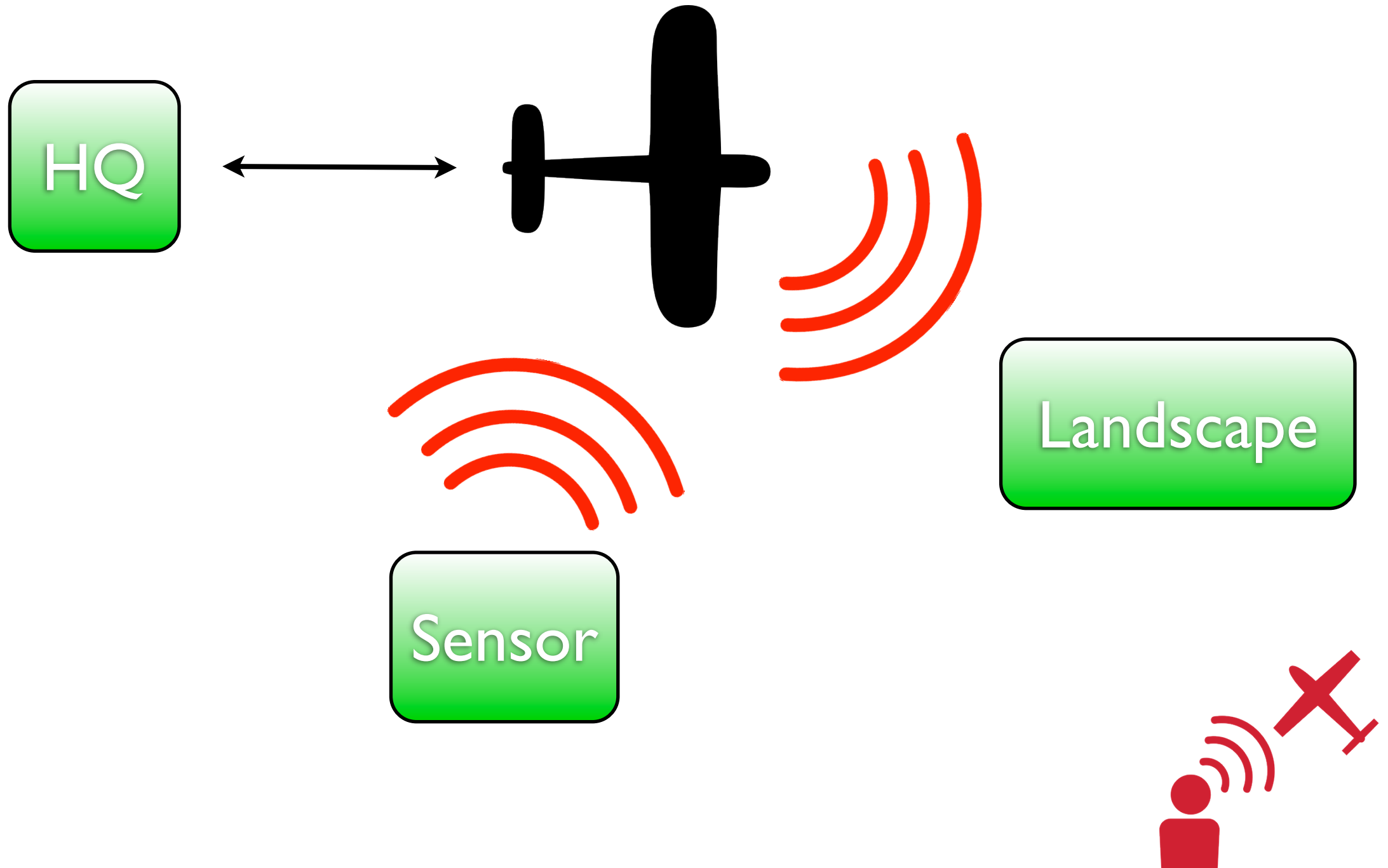


Mission Control

- Laptop with a USB connection.
- Debian 6, Ubuntu 11/10 or Windows.
- Mission Planner 1.1.89.
- VLC Player 2.0.1.
- Disaster management software at HQ
(Sahana Eden or similar)



Putting It All Together

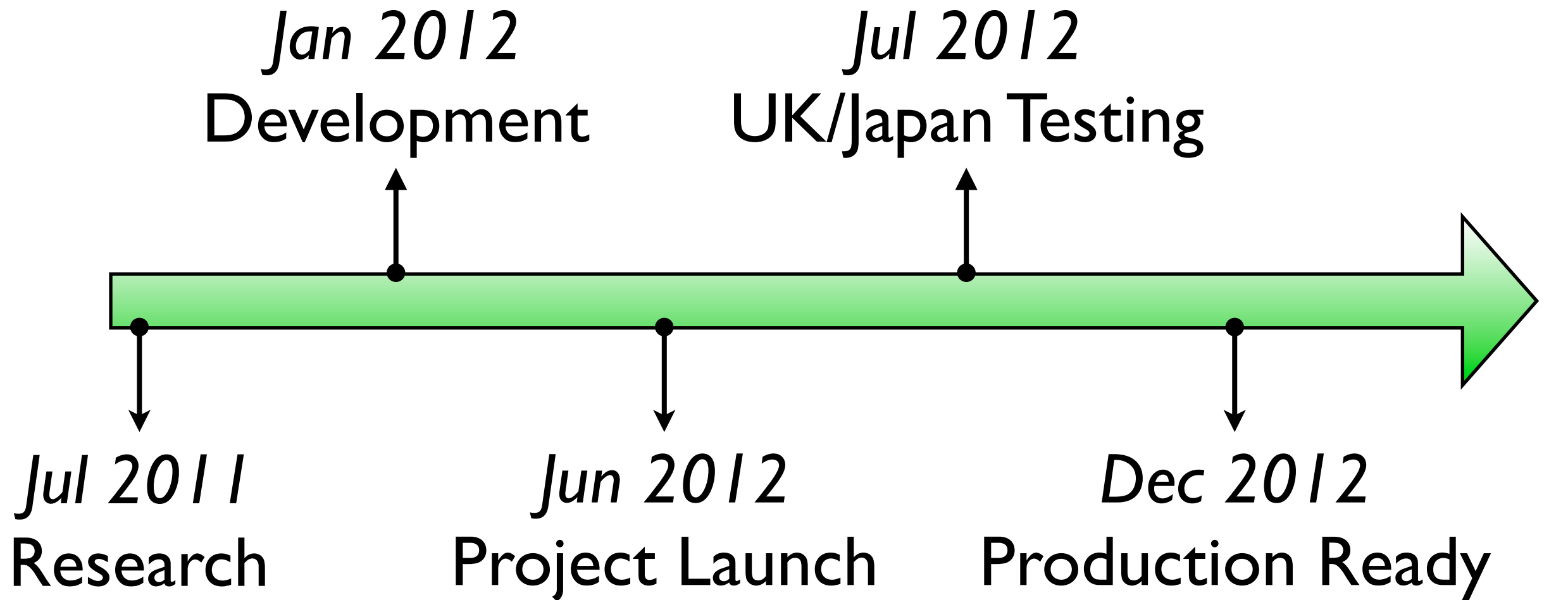


Three Cool Things

- OpenRelief solutions can provide GIS data to existing disaster management platforms.
- They can use OpenStreetMap as the basis for maps and contribute back updated data.
- They can work alongside existing processes to provide next generation abilities.



Milestones





We use crowd-sourcing for rapid development, improvement and distribution.





We are building a community to test and share our solutions around the world.



Eco-System!

 pendawn

 CodeThink



 nanode
open source



Who We Need

- Technologists who can help design, refine and advocate the OpenRelief solutions.
- Professional and volunteer emergency relief workers who can help design, test and advocate OpenRelief solutions.
- Commercial enterprises who can put these solutions into production.



Be Part Of This

- Visit www.openrelief.org
- Join our user list to get up to speed.
- Join our developer list to work on tools.
- Join our outreach list to help spread the word.



Get Our Tools

- You will find our code at:
www.gitorious.org/OpenRelief
- You will find our schematics at:
www.solderpad.com/OpenRelief



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The Future

