

Exposing the Android Camera Stack

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Agenda

Hardware Independent Section

- Overview of android.hardware.Camera

- Prominent Camera Use Cases

- High Level Architecture

- JNI Layer

- Native Camera service

- Media Subsystem Interactions

Hardware Dependent Modules

- Camera Hardware Abstraction Layer

- Camera Device Driver

- Camera Hardware Architecture

Future Trends

- Q&A



Section I

Hardware Independent Camera Stack

Overview of android.hardware.Camera

6 Classes

Camera
Camera.CameraInfo
Camera.Parameters
Camera.Size
Camera.Face
Camera.Area

7 Callback Interfaces

- Camera.AutoFocusCallback
- Camera.ErrorCallback
- Camera.FaceDetectionListener
- Camera.OnZoomChangeListener
- Camera.PictureCallback
- Camera.PreviewCallback
- Camera.ShutterCallback

Handling Camera Hardware Fragmentation

Camera.Parameters class provides a “dumb” pipe to the hardware
Hardware capabilities can be queried for capabilities.

As an example, for Video Stabilization Feature

```
isVideoStabilizationSupported()
```

```
setVideoStabilization(boolean)
```

```
getVideoStabilization()
```

Android 4.0 Camera Features

Feature	Platform Feature with API	In-built Camera Application Code	Proprietary Solution	API Level
Face Detection	✓			14
Face Recognition			✓	14
Panoramic Stitch		✓		14
Video Snapshot	✓			14
AE & AWB Lock	✓			14
Continuous Focus Mode	✓			14
Region Of Interest (AE, AWB and AF)	✓			14
Zero Shutter Lag*				14
Video Stabilization	✓			15
Live Effects on Images / Video**	✓			14

* There is no API for ZSL. It is a hardware dependent feature.

** android.media.Effect

AE : Auto Exposure

AWB : Auto White Balance

AF : Auto Focus

Prominent Camera Use Cases

Main Use Cases

Live Preview of Camera Stream

Live Preview + copy of the Frame returned to the application

Capture a frame

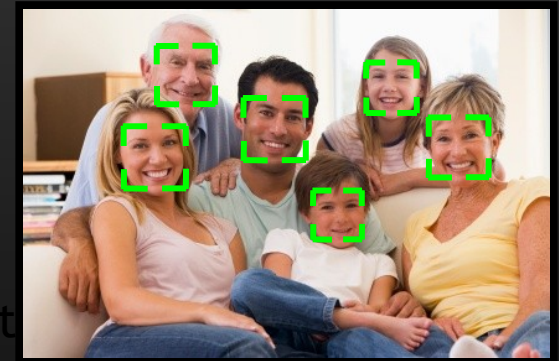
Video Recording of a Camera Stream

Secondary Use Cases

Configuring the Camera

Receiving more than an image back . e.g. face detect

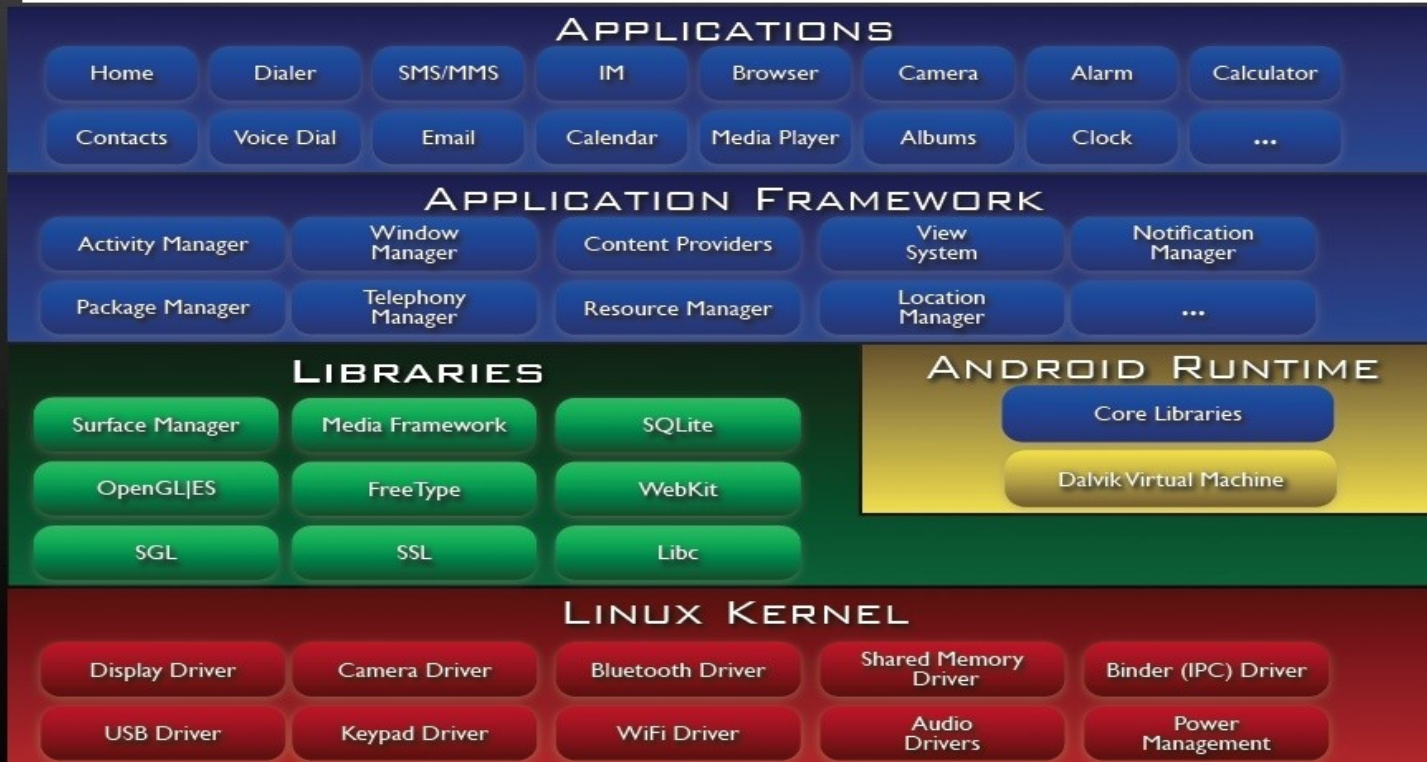
Event Callbacks: Shutter Clicked, AutoFocus Achieved



High Level Architecture

Android High Level Architecture

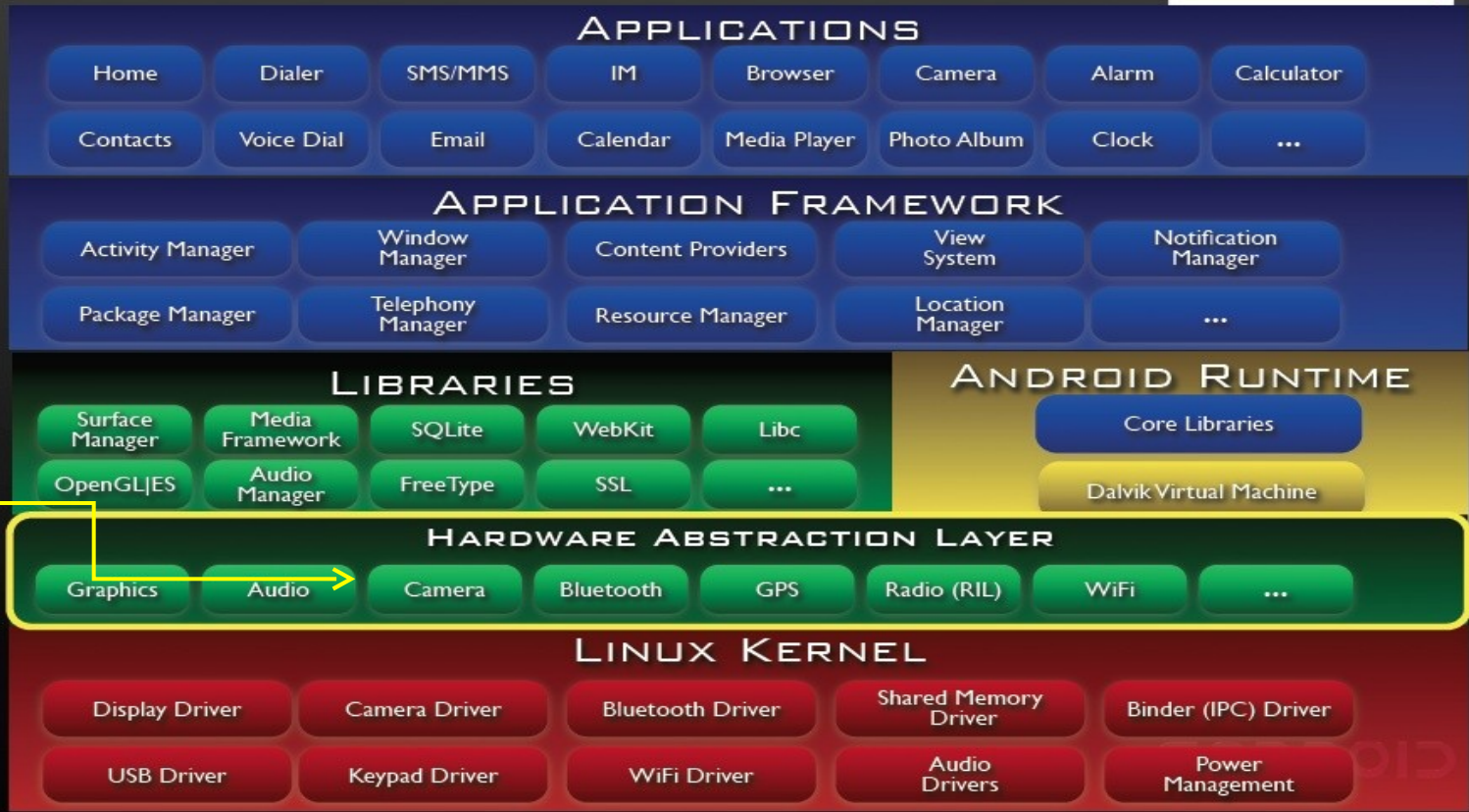
Android Anatomy



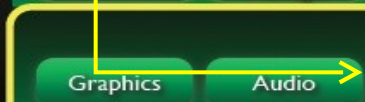
Source: Android Anatomy and Physiology, Google IO 2008

Hardware Abstraction Layer

Hardware Abstraction Layer

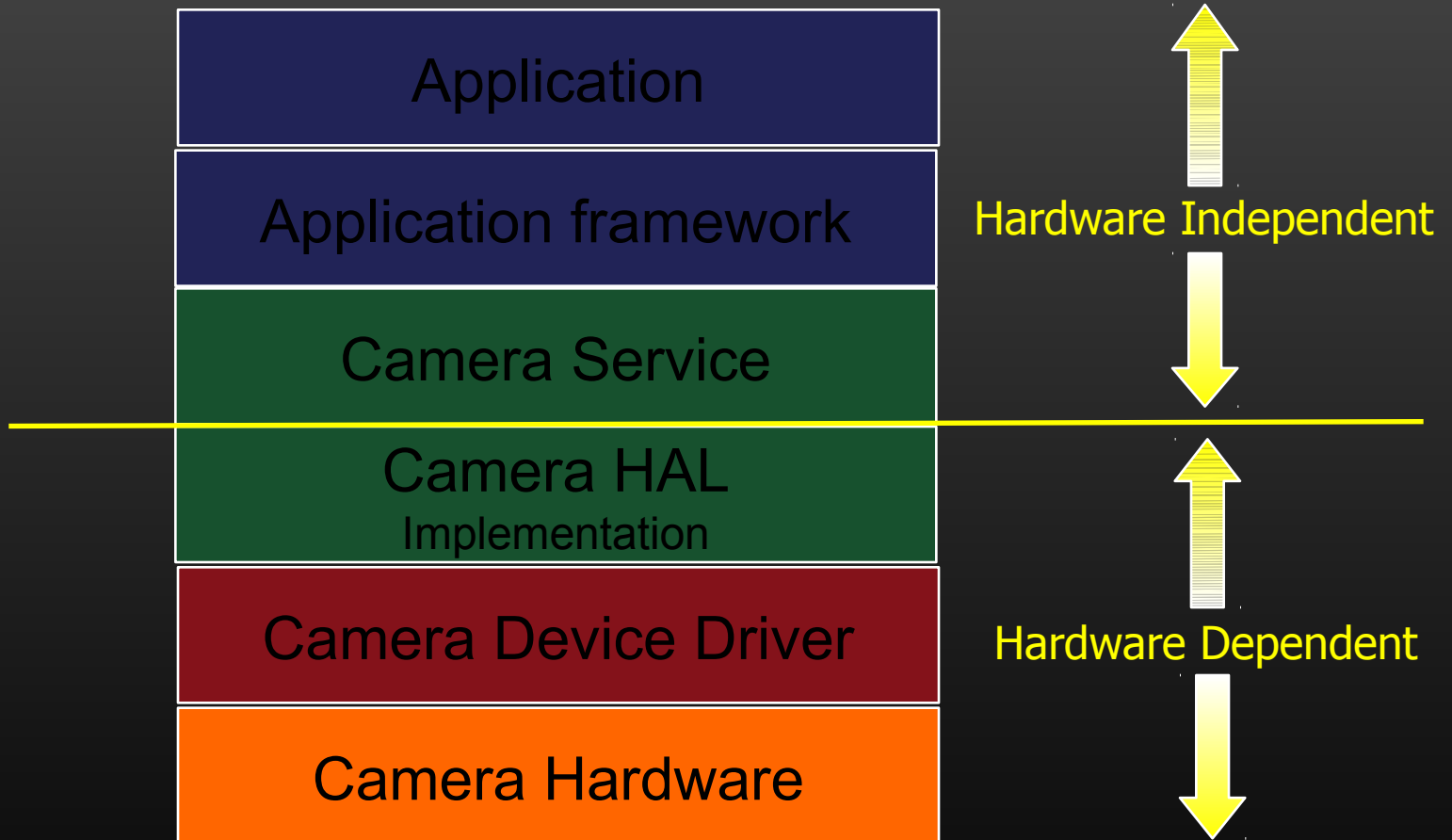


Camera



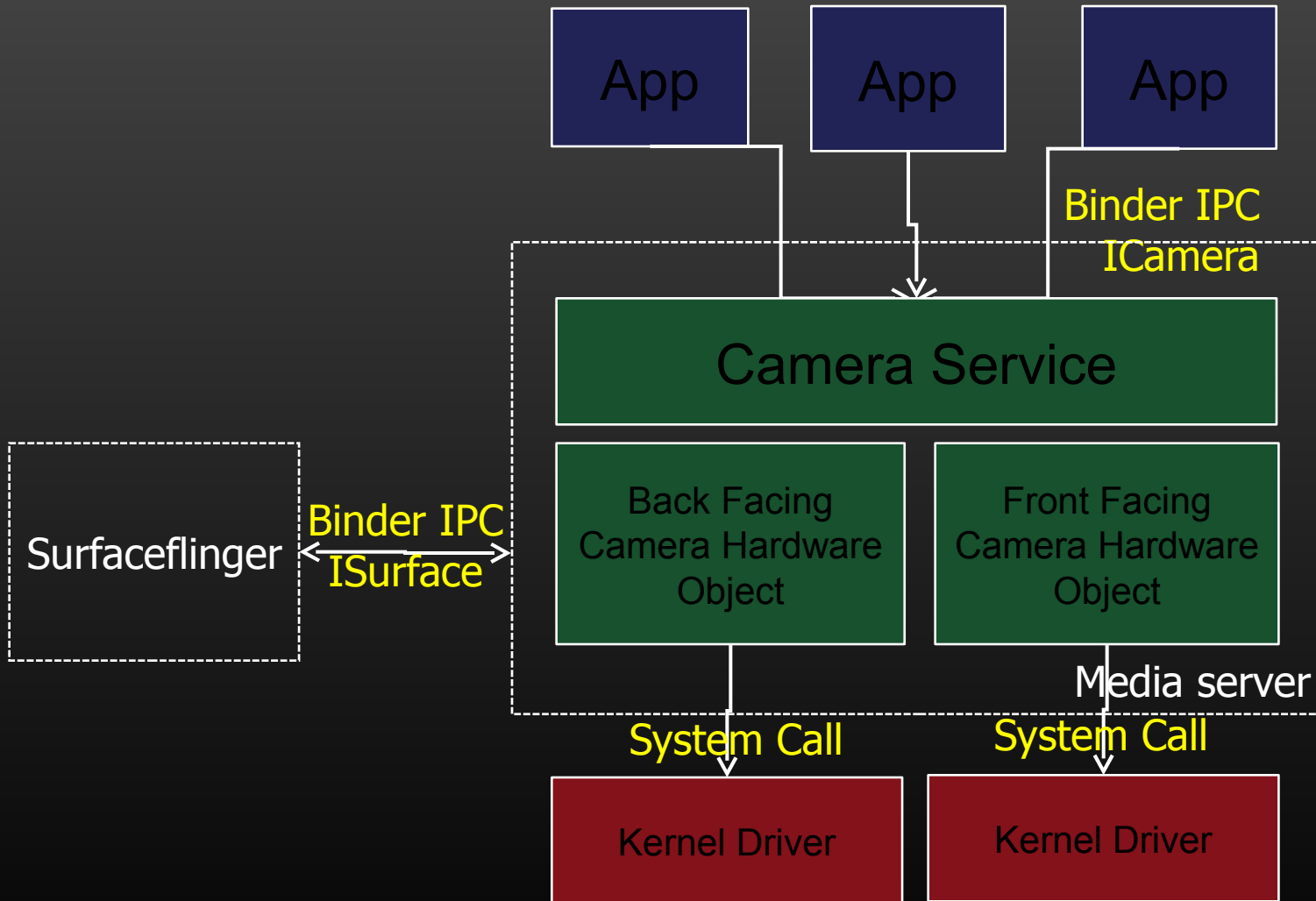
Source: Android Anatomy and Physiology, Google IO 2008

Camera Subsystem

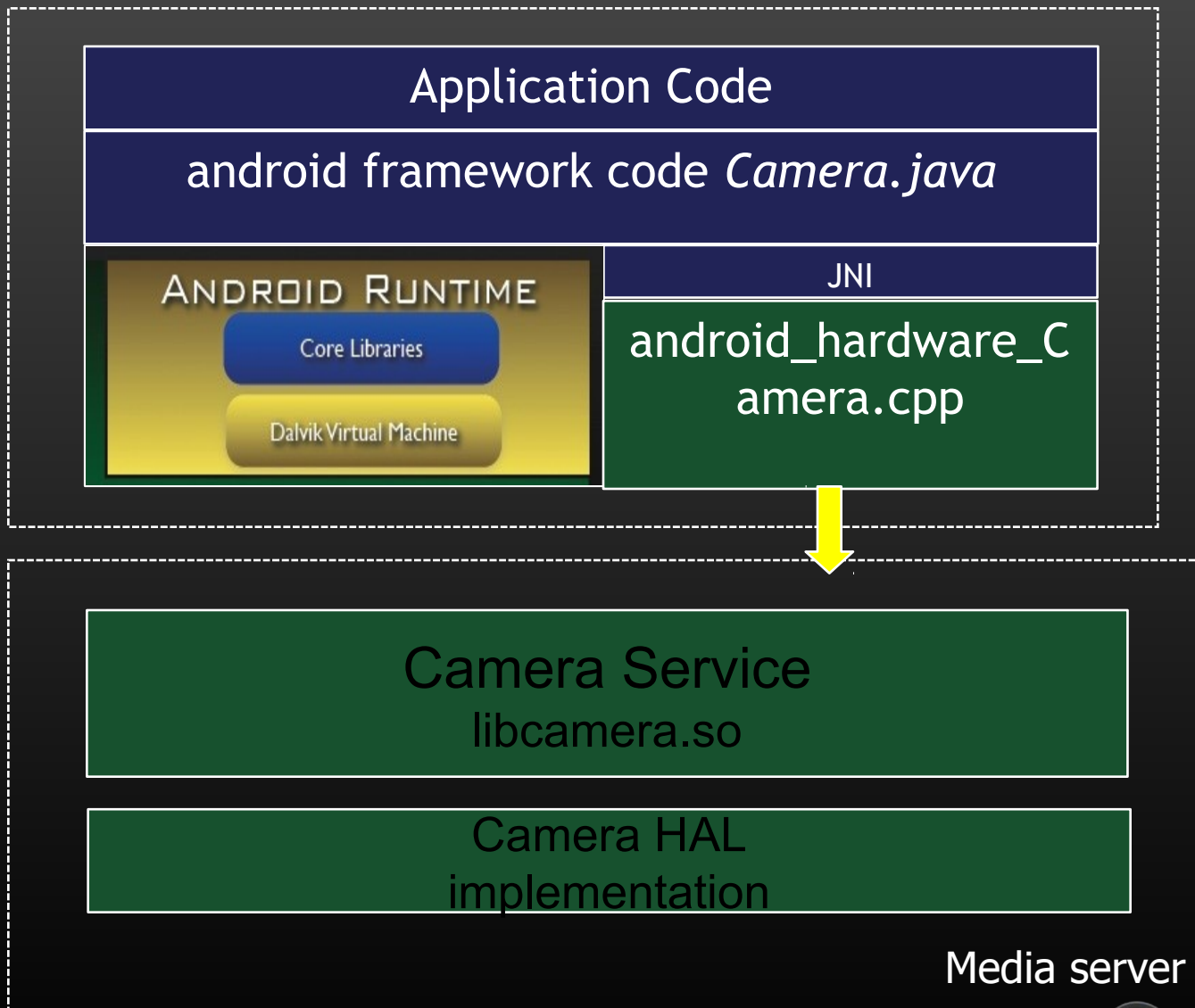


HAL = Hardware Abstraction Layer

Process View

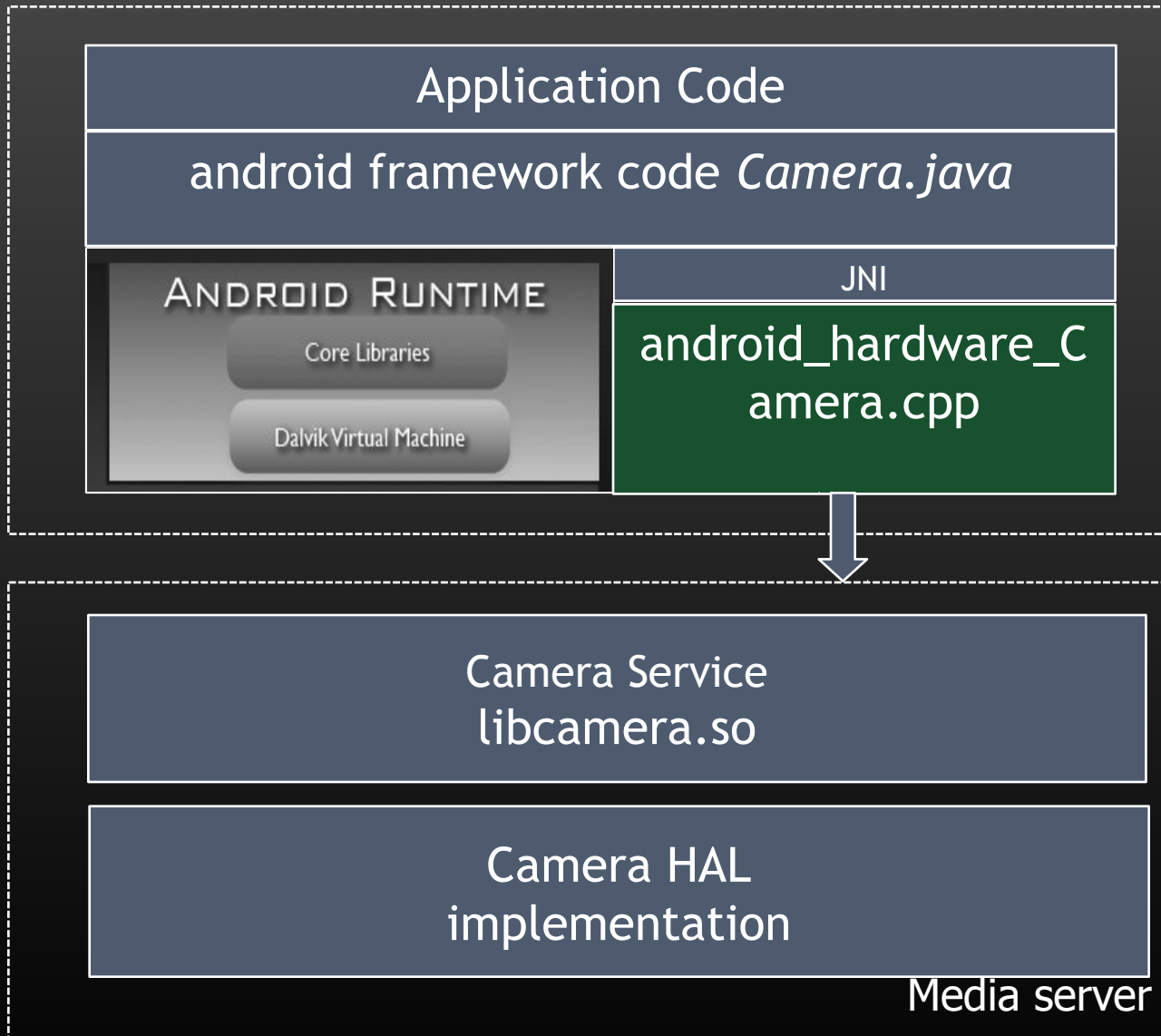


Inside the Camera App



JNI Layer

JNI Layer



android_hardware_Camera

Creates a persistent context for callbacks from native code to Java
(**JNICameraContext**)

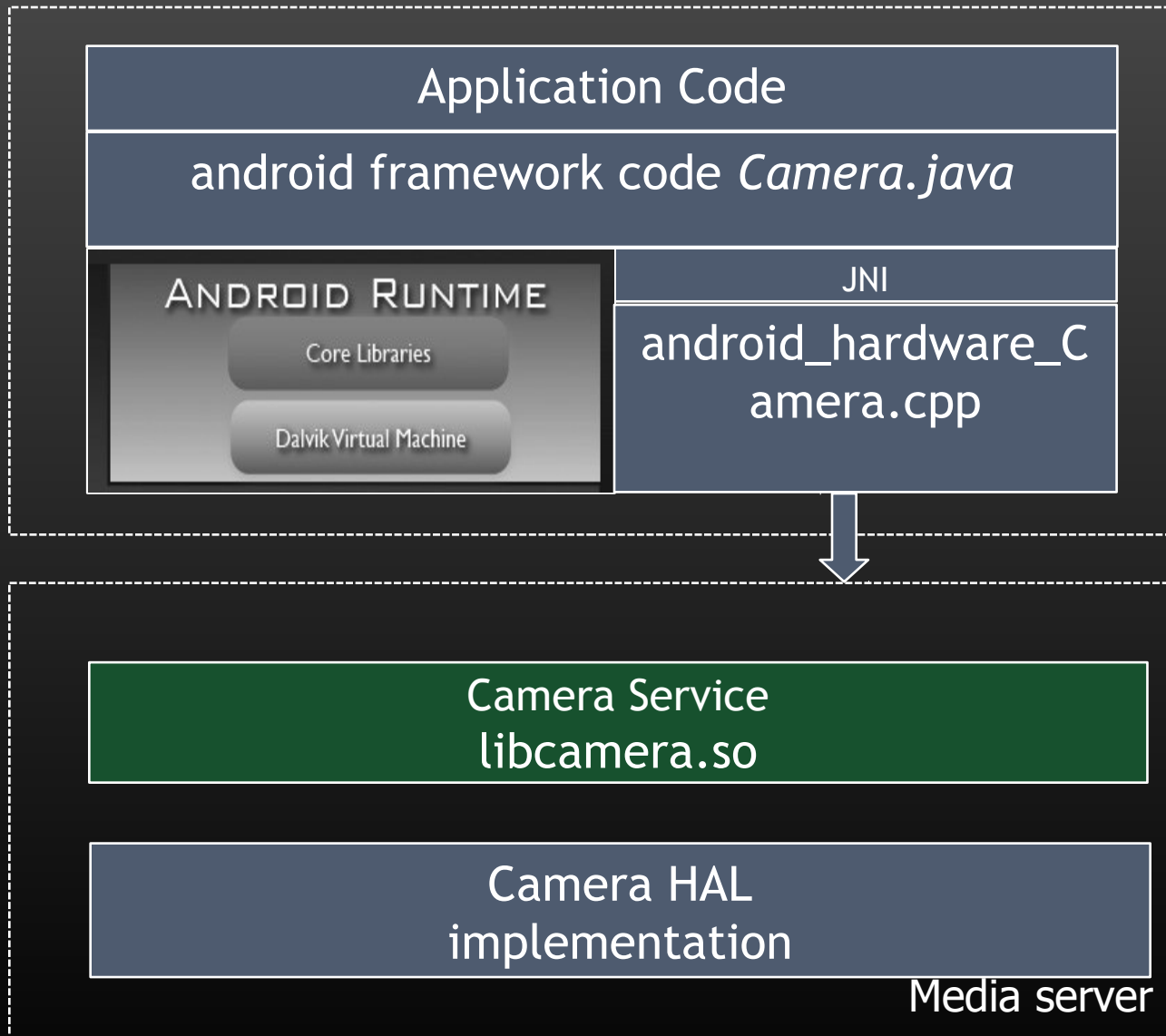
Holds references to the Java Camera, Face and Area objects.

If a Copy of the Preview Frame is requested by the app, then the copy from native to java buffers is done here.

Allocates Memory from the Java memory heap for JPEG images.

Camera Service

Camera Service



Camera Service

Resource Manager for the Camera Hardware Asset

Runs in the media server process

It is a shared library libcameraservice.so

Main Functions:

Permission check android.permission.CAMERA

Ensures only one Client connects to a Camera Hardware Object

Ensures each Process connects to a single Camera Hardware Object

Redirects callbacks back to the app layer

Accessed over IBinder Interface

Number of Cameras Available

CameraInfo Details

Camera Service (contd.)

Android.mk file

frameworks/base/media/mediaserver/Android.mk

```
LOCAL_SHARED_LIBRARIES := \
```

```
    libaudioflinger \
```

```
    libcameraservice \
```

```
    libmediaplayerservice \
```

```
    libutils \
```

```
    libbinder
```

Gets instantiated as along with other components of the media server

```
AudioFlinger::instantiate();
```

```
MediaPlayerService::instantiate();
```

```
CameraService::instantiate();
```

```
AudioPolicyService::instantiate();
```

Interaction with the Media Subsystem

ICameraRecordingProxy and **ICameraRecordingProxyListener** were introduced in Android 4.0

Allow apps to use the camera subsystem while the MediaRecorder is recording the video frames.

ICameraRecordingProxy is a proxy of Icamera

- startRecording

- stopRecording

- releaseRecordingFrame

ICameraRecordingProxyListener is an interface that allows the recorder to receive video frames during recording.

- dataCallbackTimestamp

Android Open Source Project (AOSP) Structure

Android Framework

Java: `frameworks/base/core/java/android/hardware`

JNI: `frameworks/base/core/jni`

Camera Service

`frameworks/base/services/camera/libcameraservice/`

IBinder Interfaces

`frameworks/base/libs/camera/ICamera.h`

Camera HAL Interface

`frameworks/base/services/camera/libcameraservice`

Camera HAL

`hardware/<vendor>/camera` (typically)



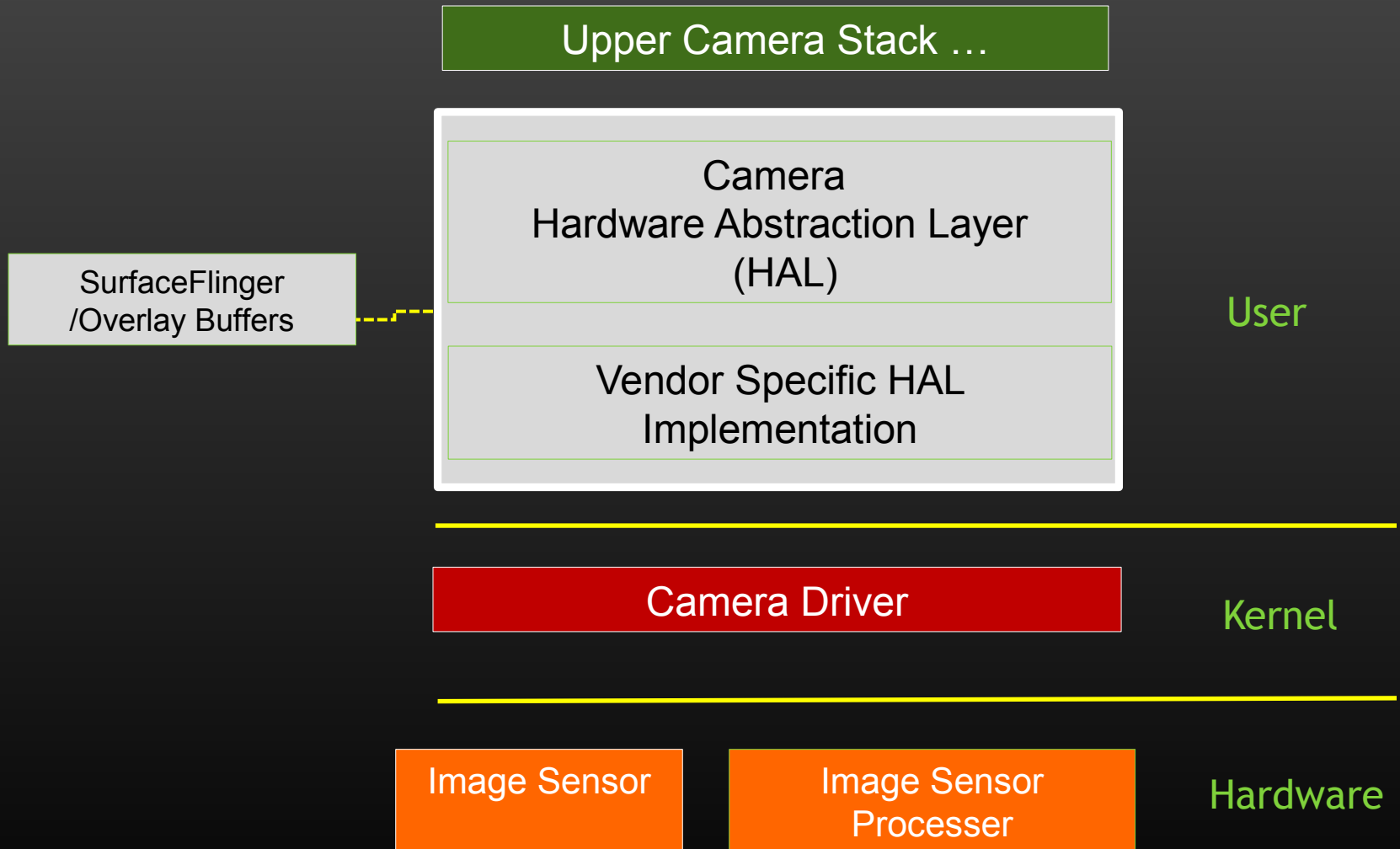
Section II

Hardware-Dependent Camera Stack

Camera Hardware Abstraction Layer

Review of a Typical Implementation

Camera Stack - Camera HAL



Android CameraHAL Library

The Camera Hardware Abstraction Layer (HAL) is a library that is specific to the camera hardware platform

Written by hardware vendors (Qualcomm, TI, others)

CameraHAL maps Android Camera Service calls to driver functions

Android Froyo uses CameraHardwareInterface.h wrapper

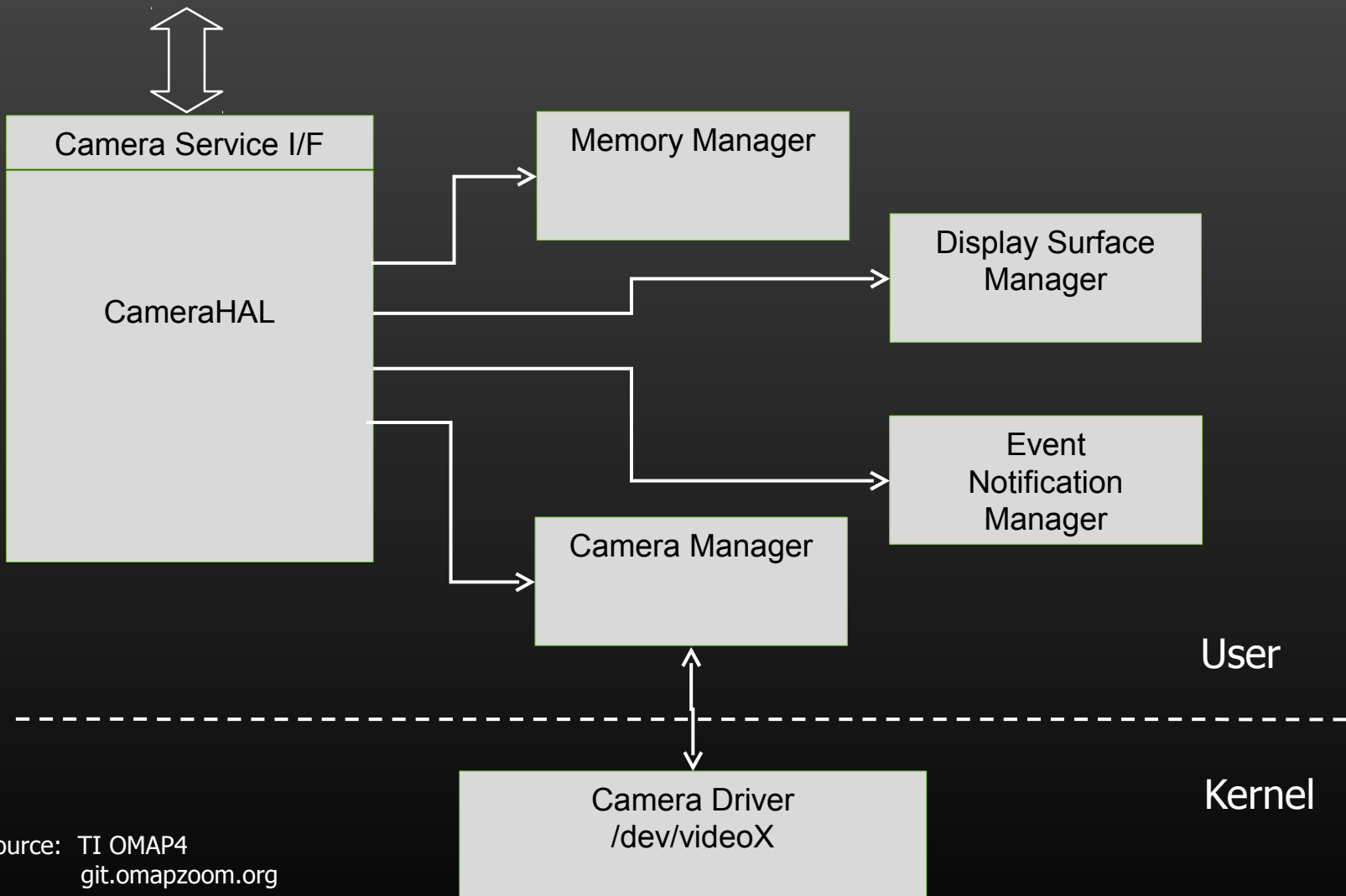
Ice Cream Sandwich (ICS) and above use camera.h

CameraHAL low level interface communicates with the kernel level driver

It can support interfaces including Video for Linux 2 (V4L2) or OpenMax (OMX)

Communicates with the driver through file I/O calls (open, close, input/output controls (IOCTL), etc)

Sample CameraHAL Functional Diagram



Source: TI OMAP4
git.omapzoom.org

CameraHAL Block Diagram Discussion (1)

Parts of the previous block diagram are hardware vendor specific

May be different for each vendor and target platform

CameraHAL

Initialization - initialize the CameraHAL block and the target device driver

Camera Services interface - Handle each Camera Service request, dispatch requests to the appropriate functional block

Camera State machine - maintain the camera state through different API calls (e.g., preview, capture, recording, focus enable, etc).

Memory Manager

Cameras are memory intensive devices

On request, allocate buffers for preview, capture and other functions

Display Surface Manager

Controls preview and video displaying - helps to coordinate with the camera manager block

CameraHAL Block Diagram Discussion (2)

Display Surface Manager (cont)

- Communicates to the display when a frame is ready for preview

- Signals to the Camera Manager when the image buffer can be re-queued

Event Notification Manager

- Supported callbacks include notify, data and timestamp

 - Notify - call on camera error, shutter, focus, zoom events or raw image notify event

 - Timestamp - call on video frame event

 - Data - call on preview, postview, compressed image, and other capture events

- Call backs types are separated at the Camera Service level

Camera Manager

- Handle camera activities

 - Setting parameters

 - Preview and snapshot callback

CameraHAL Preview Discussion

The following slides discuss the preview use case

Preview - displaying the camera image on the device display in real time

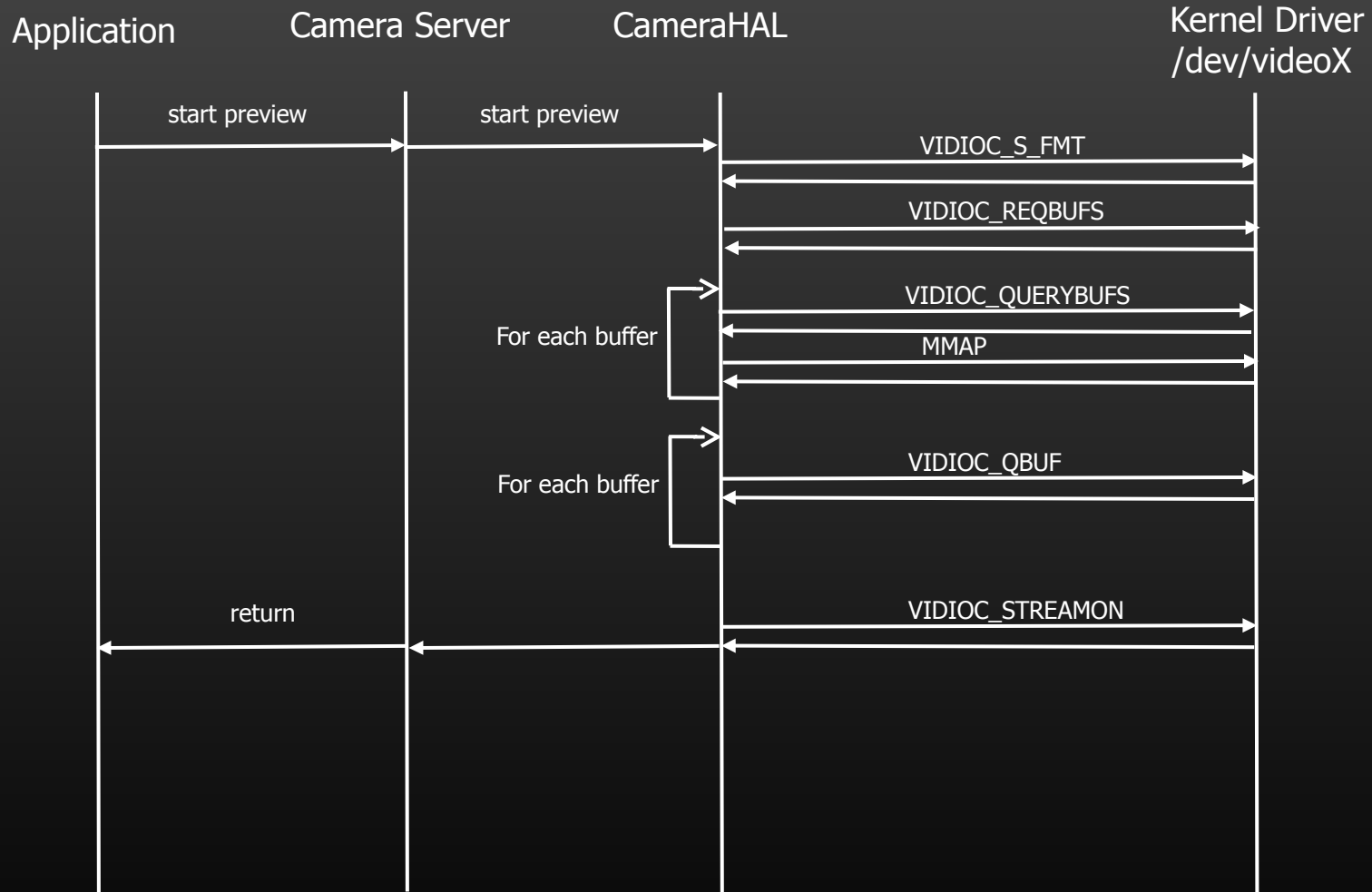
The startPreview application call initiates image preview

A single application level call results in a chain of CameraHAL and driver events

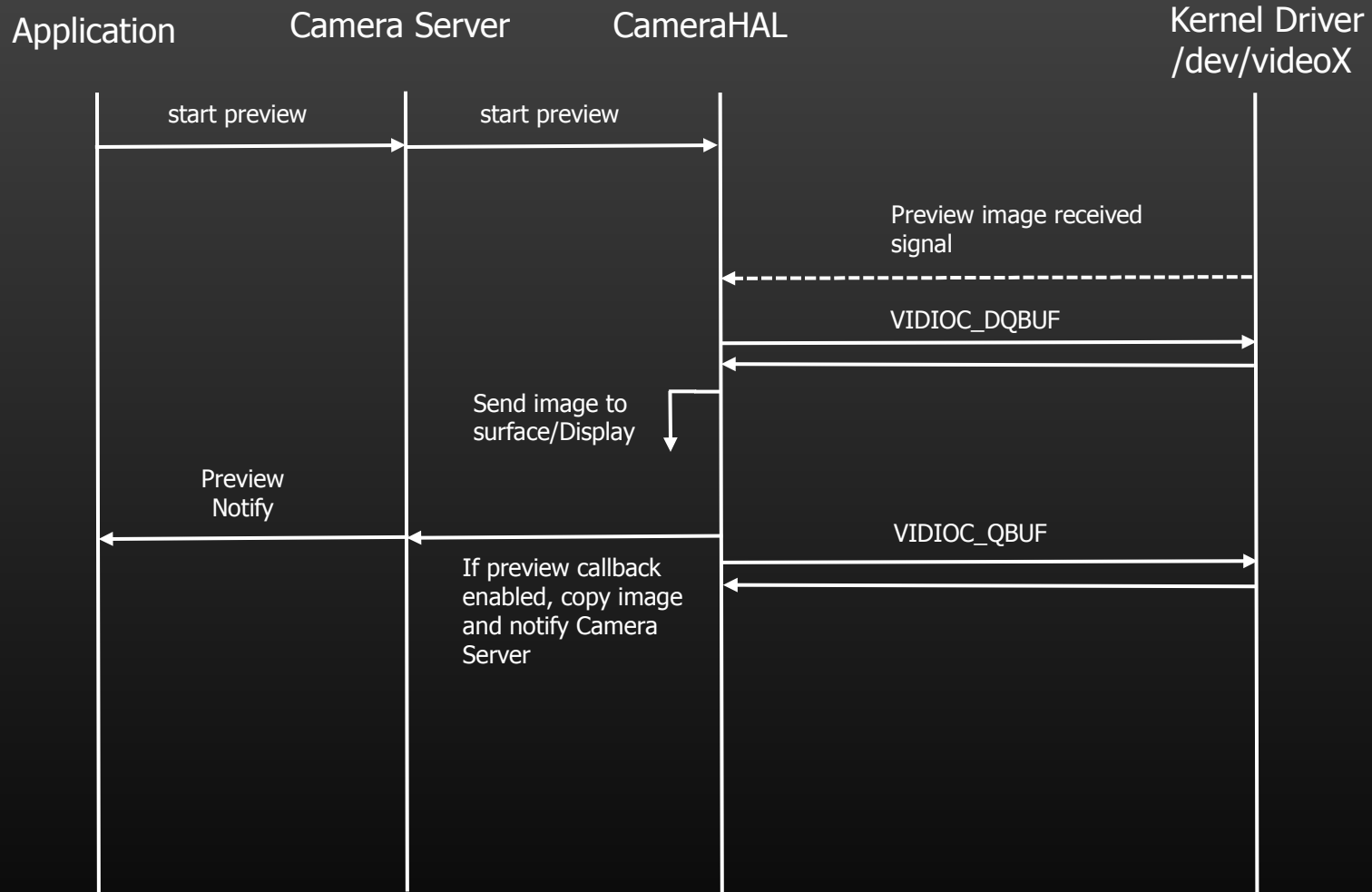
Preview continues until the stopPreview() application call

During preview, no application interaction unless a preview callback is registered

Preview Start Up Sequence Diagram (V4L2)



Preview Operation Sequence Diagram (V4L2)



Camera Preview Interaction with the Display Subsystem

Matching the timing of 2 events

- Preview frames arrive asynchronously from the camera

- The display subsystem refreshes the display at regular intervals

- Potential mismatch between these 2 systems

Sending the preview image to the display subsystem

- The preview frame is removed from the V4L2 queue of buffers

- The frame is sent to the display subsystem

 - The frame memory is shared by the display subsystem

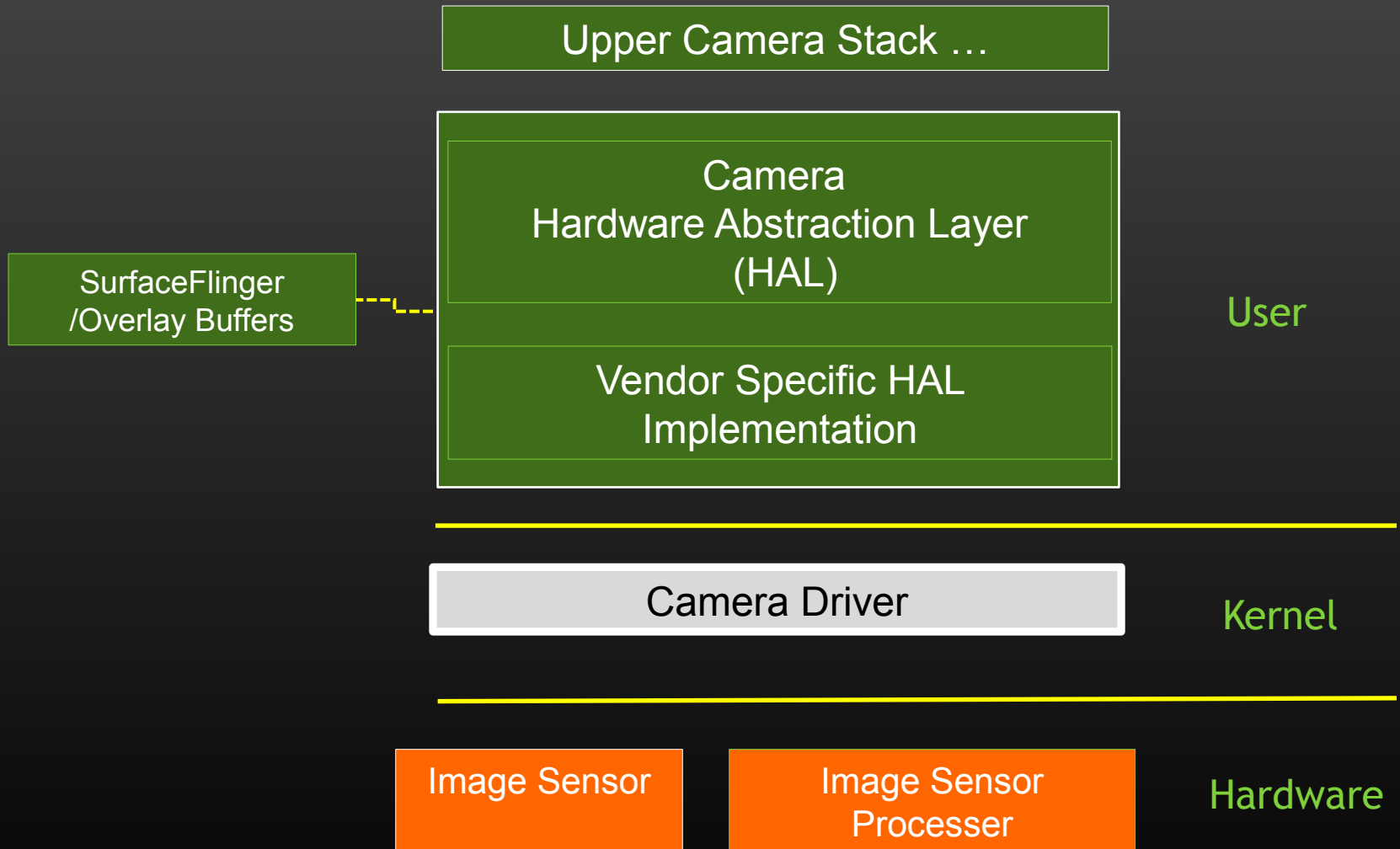
 - Or the frame is copied to a buffer for display subsystem use

- The preview frame may be copied to a user space buffer if preview callback is enabled

- The frame is returned to the V4L2 queue of buffers when done

Camera Device Driver

Camera Stack - Camera Driver



Android Kernel Camera Driver

The kernel driver presents a standard interface for different types of camera hardware

Camera hardware specific attributes are (usually) handled by the low level kernel driver

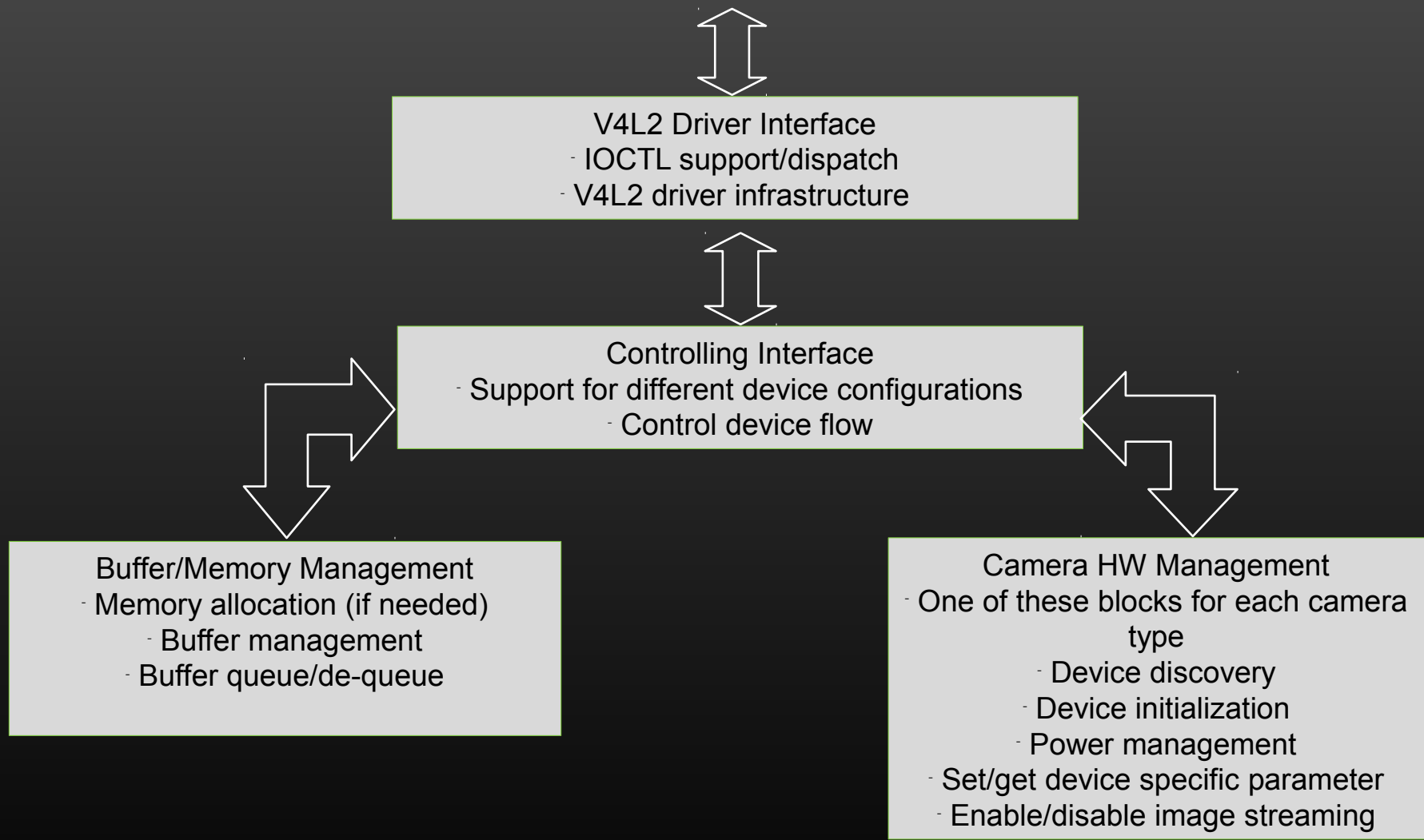
Image Sensor Processor (ISP) vs. smart image sensor - differences are handled at the driver level

For Android, Video for Linux 2 (V4L2) is used in many implementations

V4L2 has been in existence for many years

OpenMax (OMX) is also used for a low level driver interface by some vendors.

V4L2 Kernel Driver Block Diagram



Android Linux Kernel Functionality

Support for multiple camera types

Camera specific code is localized to one file (the subdev device)

Compile time option to add other cameras (one driver can support many different camera hardwares)

More cameras mean a longer start up time since the driver is searching for each device

The driver manages the underlying hardware topology (e.g., ISP + sensor, smart sensor)

For two or more cameras, the V4L2 driver creates additional device nodes

Devices show up as /dev/video0 (primary), /dev/video1 (secondary), ...

V4L2 Kernel Driver Resources

Memory

Memory can be either driver-allocated or user-provided

Moving image from the camera to memory should be done through hardware DMA (Direct Memory Access)

Hardware memory management required to avoid contiguous memory requirement

Interrupts

Camera ports support for interrupts on events such as frame start, finish, focus events, etc.

Camera Control: I2C/SPI

Communications with the camera is usually done with I2C by either writing or reading sensor registers.

I2C is somewhat slow, this limits the number of register accesses during a frame. SPI (Serial Peripheral Interface) is an alternative to I2C.

Control Signals/Power/GPIO

All controlled by the low level driver

Power

Sensor power management is critical to embedded device operation

Save power by disabling the sensor and sensor processor when not used

V4L2 Driver Buffer Management

One or more buffers are supported

User buffers or kernel-allocated buffers are supported

Buffers are treated the same for preview, capture, video
(output resolution does not matter)

Buffers are queued to a circular list

Buffer filling starts when the V4L2 Stream_On command
is executed

Once filled, the CameraHAL de-queues a buffer,
processes the buffer, then re-queues the buffer

The Stream_Off command causes all buffer to be
released

Typical Android V4L2 Start up Sequence

The V4L2 call for the preview are given below

V4L2 Call	Title	Comments
V4L2_Open()	Open a V4L2 Device	
VIDIOC_S_FMT	IOCTL: Set format	Set both resolution and output pixel format
VIDIOC_G_PARM	IOCTL: Get camera parameter	Get the camera frame rate
VIDIOC_S_PARM	IOCTL: Set camera parameter	Set the camera frame rate
VIDIOC_CROPCAP	IOCTL: Get the camera cropping capabilities	Get the current crop rectangle
VIDIOC_S_CROP	IOCTL: Set the cropping rectangle	Set the desired cropping rectangle
VIDIOC_REQBUFS	IOCTL: Request camera buffers	Request buffer support from the driver (user vs. kernel)
Loop: VIDIOC_QUERYBUF	IOCTL: Return buffer address information	Used for mapping buffers to user space
V4L2_MMAP	Memory map buffers to user space	Make buffers visible to user applications

Typical V4L2 Start up Sequence

V4L2 driver start up sequence (cont)

Typ

V4L2 Call	Title	Comments
Loop: VIDIOC_QBUF	IOCTL: Add buffer to queue	Queue of buffers the kernel manages
VIDIOC_STREAM_ON	IOCTL: Start image streaming	Camera/Driver starts filling the queued buffers

V4L2 Call	Title	Comments
VIDIOC_STREAM_OFF	IOCTL: Stop image streaming	Stop camera/driver streaming
V4L2_Close()	Close the camera device	Disable camera operations, free resources

V4L2 Driver Directions

Other Topics

V4L2 Media Controller Architecture

Exposing the hardware image processor to the calling application

Allows for greater programmer control

Supported only on open source architectures

Proprietary ISP software moves to user space

Many ISP providers wish to hide their hardware

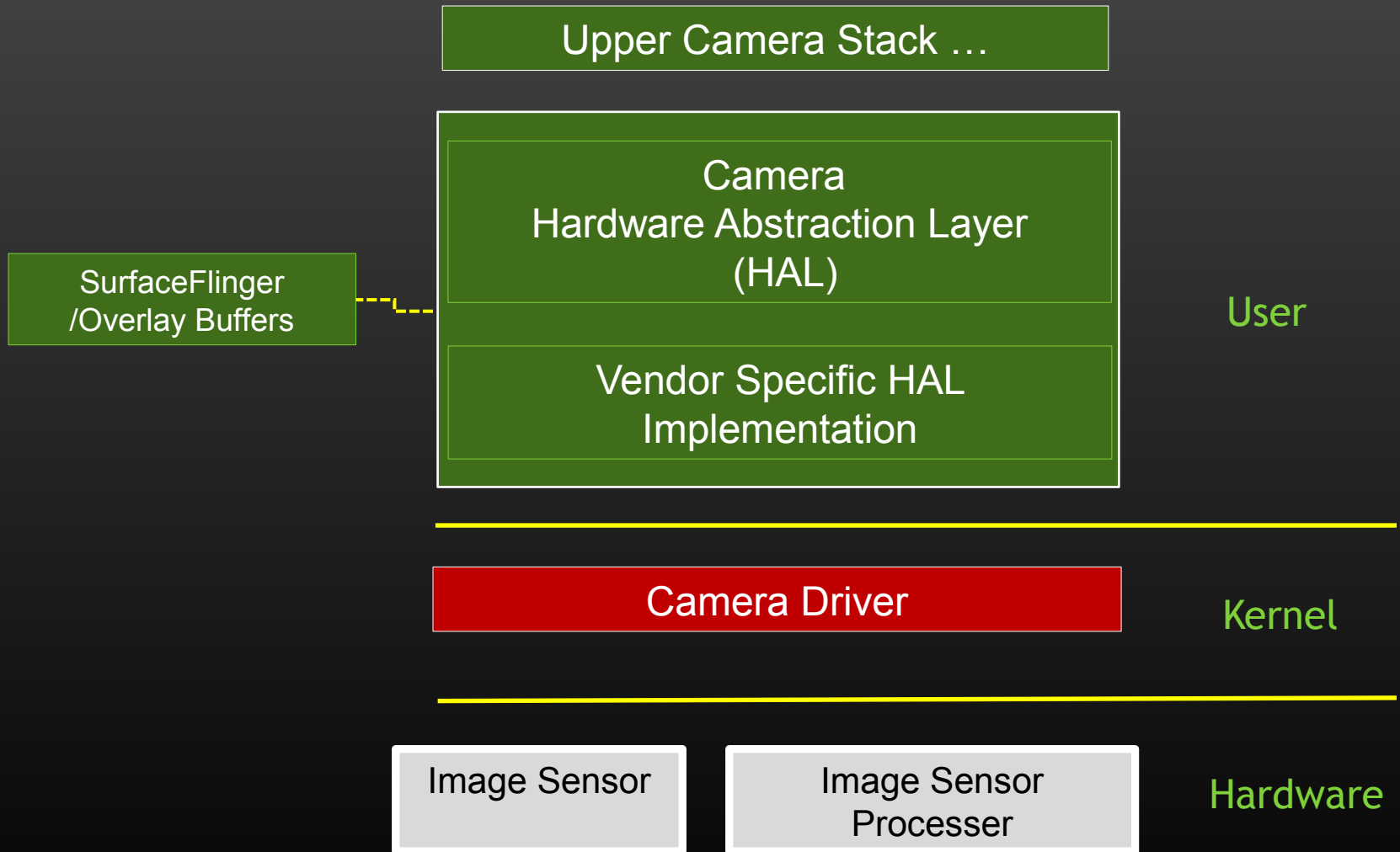
Moving ISP code to user space handles this (avoid kernel open source issues)

Driver source code location:

{kernel sources}/drivers/media/video

Camera Hardware Overview

Camera Stack - Camera Hardware



Camera Hardware Introduction

Types of Sensor Hardware

Raw or Bayer Sensor

Outputs a Bayer (unprocessed) image



Used with internal or external Image Sensor Processor (ISP)

Internal ISP - System Processor and ISP bundled together

External ISP - External companion chip

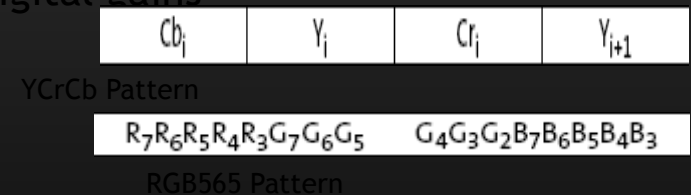
Controls include exposure time and analog/digital gains

Smart or System On a Chip (SOC) Sensor

ISP built into the sensor

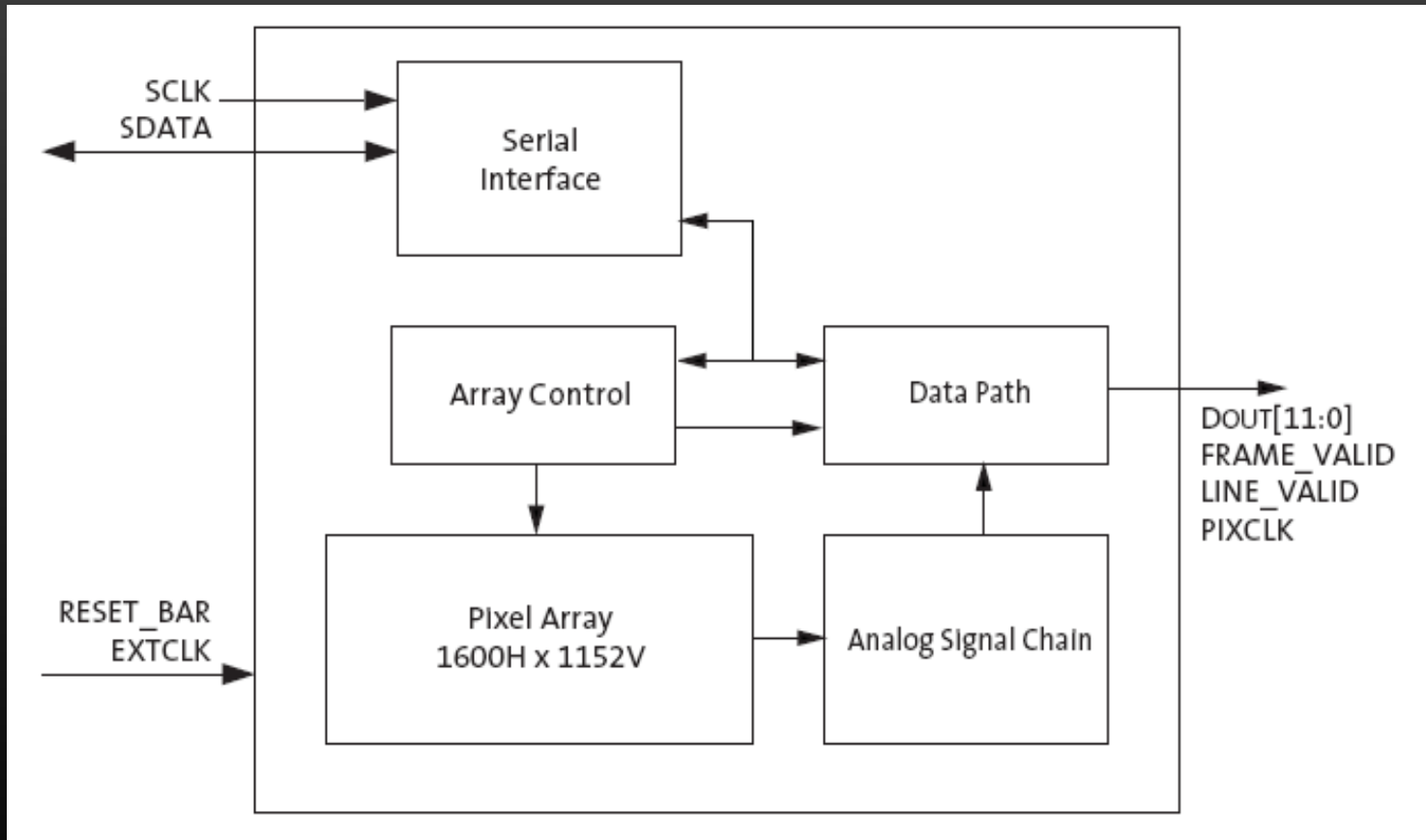
Outputs processed YUV/RGB/Other formats

Controls include exposure, white balance, gamma correction, and many others



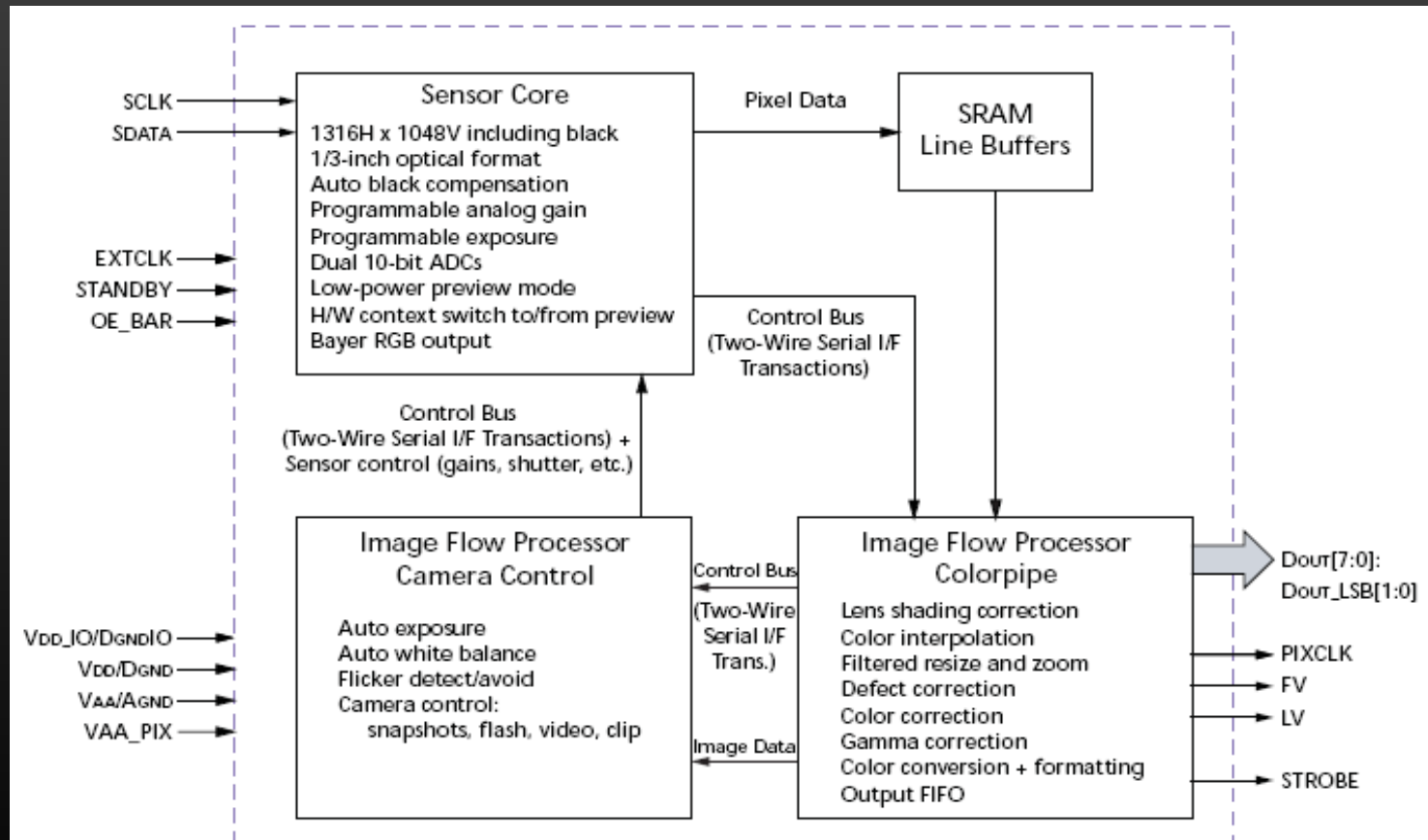
Bayer Sensor Block Diagram

Example - MT9M032 - 1.6MP Image Sensor



SOC Sensor Block Diagram

Example - MT9M131 - 1.3 MP Image Sensor



Camera Hardware Inputs/Outputs

Controlled by the sensor driver

Inputs:

- Power/Ground (analog, digital power/grounds)

- Control Signals

 - Reset - reset the camera to a default state

 - Standby - place the camera in low power standby mode

 - GPIO, others - control camera peripherals such as autofocus, flash, etc.

- Clock In (system clock in)

- Register control through I2C, SPI, or others

Output

- Data Output

 - Parallel (8, 10, 12, 14 bits)

 - Serial (MIPI)

- Control Signals (frame/line valid)

- Clock Out (pixel clock out)



A Peek into the Future

Camera Application Trends

Android Applications - memory limitation 16MB ~ 24MB

Higher pixel sizes and Bursty modes put a strain on the system

Computer Vision Applications go mainstream

APIs on Object Tracking, Gesture Recognition become more common place

Computation Photography application

Developers get fine grained control of flash and camera

Camera Hardware Trends

Back Side Illumination(BSI) vs. Front Side Illumination(FSI)

BSI can add up to 30% more light gathering capability

Smaller Pixels

Constant push to reduce pixel and sensor package sizes

Faster data output rates, higher clock speeds

1080p30, 1080p60

Serial data interfaces enable increased sensor output speeds

High Dynamic Range

Ability to capture larger exposure range

3D Imaging

Use of 2 cameras to generate a 3D image

Q&A

References

<http://developer.android.com/>

<http://www.codeaurora.org>

<http://omappedia.org>

<http://source.android.com>

